

# ECEN474: (Analog) VLSI Circuit Design

## Fall 2011

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### Lecture 38: Distortion



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# Agenda

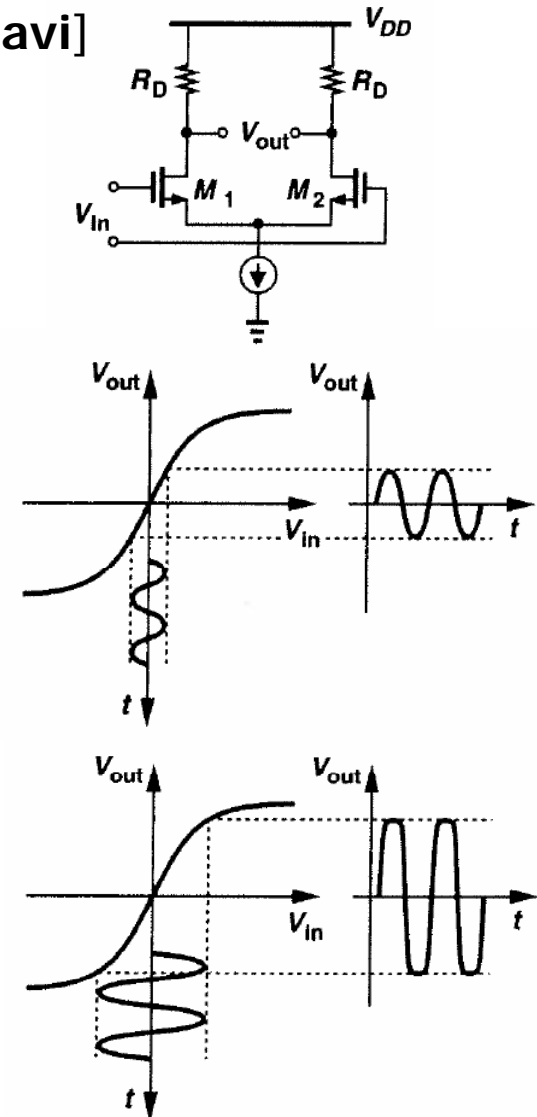
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- Circuit Nonlinearity
- Harmonic Distortion
- Examples
  - Common-Source Amplifier
  - Differential Pair
- Linearization Techniques
- Course Evaluations

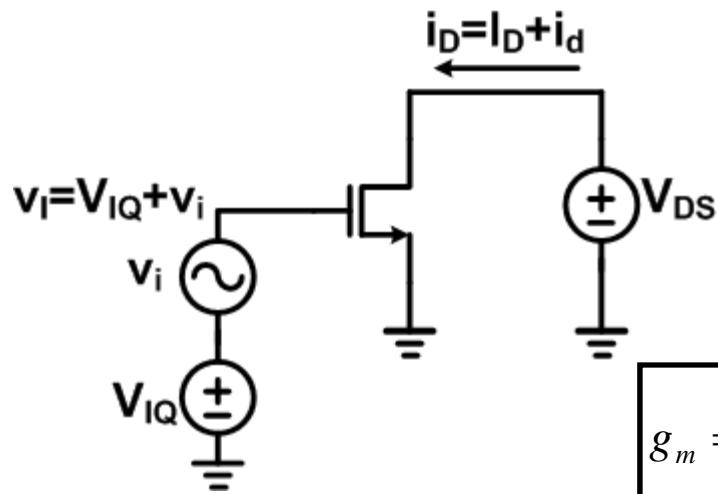
# Circuit Nonlinearity

- Circuits generally exhibit nonlinear behavior if the input signal is large enough
  - Linearized small-signal models only model “small-signal” behavior about a given operating point
- This lecture covers low-frequency “memory-less” distortion
  - High-frequency distortion is much more complex
- It also assumes a constant region of operation (saturation)
  - Signal is large enough for distortion, but not large enough to enter triode

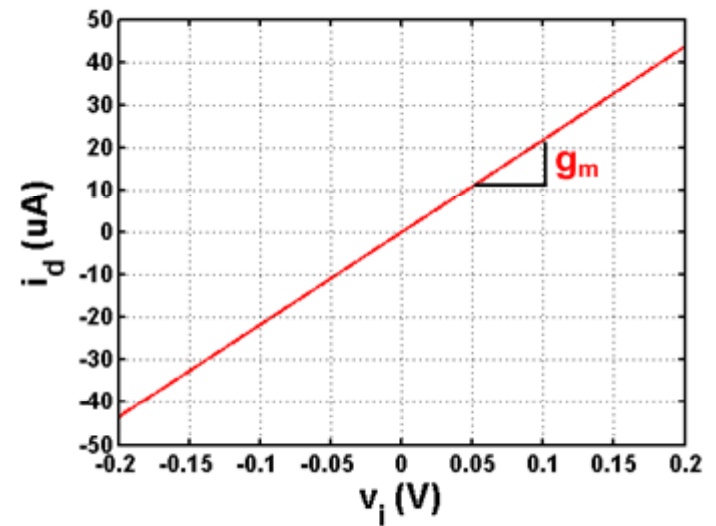
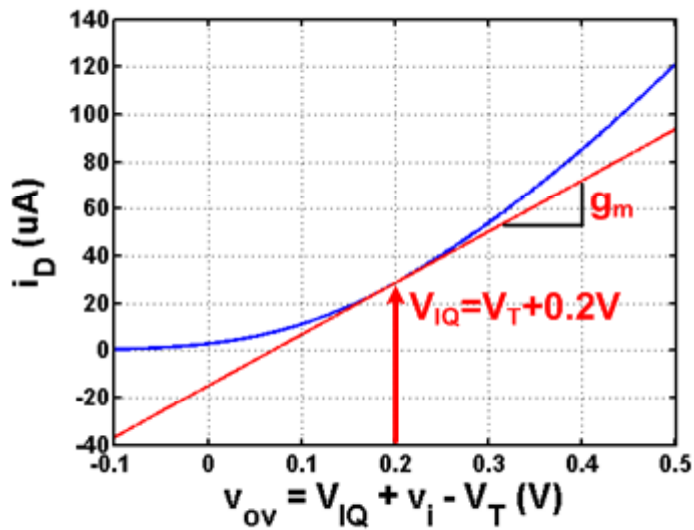
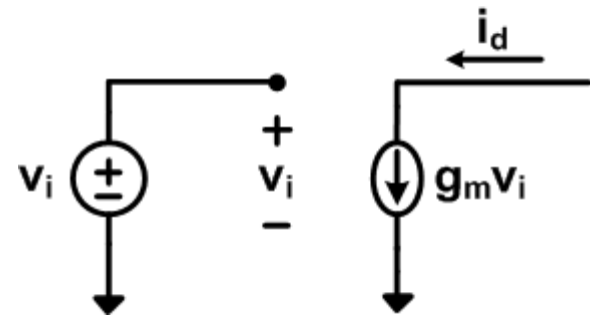
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# Small-Signal AC Model



$$g_m = \left. \frac{\partial I_D}{\partial V_I} \right|_{V_I = V_{IQ}} = f'(V_{IQ})$$



# Taylor Series Model

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We can model the nonlinear expression with a Taylor Series at  $V_{IQ}$

$$f(v_I) = f(V_{IQ}) + \frac{f'(V_{IQ})}{1!}(v_I - V_{IQ}) + \frac{f''(V_{IQ})}{2!}(v_I - V_{IQ})^2 + \frac{f'''(V_{IQ})}{3!}(v_I - V_{IQ})^3 + \dots$$

The small - signal behavior about  $V_{IQ}$  can be modeled with

$$v_i = v_I - V_{IQ} \quad \text{and} \quad i_d = i_D - I_D = f(v_I) - f(V_{IQ})$$

We can express  $i_d$  as

$$i_d = a_1 v_i + a_2 v_i^2 + a_3 v_i^3 + \dots$$

where

$$a_m = \frac{f^{(m)}(V_{IQ})}{m!}$$

$$a_1 = g_m \quad a_2 = \frac{1}{2} g'_m \quad a_3 = \frac{1}{6} g''_m$$

- For hand analysis, it is often sufficient to truncate the Taylor Series after the 3<sup>rd</sup> to 5<sup>th</sup> term

# Harmonic Distortion Analysis

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**Applying a sinusoidal input signal to the Taylor Series model**

$$v_i = V_m \cos(\omega t)$$

$$i_d = a_1 V_m \cos(\omega t) + a_2 [V_m \cos(\omega t)]^2 + a_3 [V_m \cos(\omega t)]^3 + \dots$$

**Recall**  $\cos^2(x) = \frac{1}{2}[\cos(2x) + 1]$  **and**  $\cos^3(x) = \frac{1}{4}[\cos(3x) + 3\cos(x)]$

$$i_d = \left[ \frac{1}{2} a_2 V_m^2 \right] \quad \text{DC Shift}$$
$$+ \left[ a_1 V_m + \frac{3}{4} a_3 V_m^3 \right] \cos(\omega t) \quad \text{Fundamental Component}$$
$$+ \left[ \frac{1}{2} a_2 V_m^2 \right] \cos(2\omega t) + \left[ \frac{1}{4} a_3 V_m^3 \right] \cos(3\omega t) + \dots \quad \text{Harmonic Components}$$

- The quadratic term  $a_2$  generates a 2<sup>nd</sup> harmonic tone and a DC shift
- The cubic term  $a_3$  generates a third harmonic term and modifies the fundamental tone amplitude with gain compression ( $a_3 < 0$ ) or gain expansion ( $a_3 > 0$ )

# Harmonic Distortion Metrics

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$$HD_2 = \frac{\text{second harmonic distortion signal amplitude}}{\text{fundamental signal amplitude}}$$

$$HD_3 = \frac{\text{third harmonic distortion signal amplitude}}{\text{fundamental signal amplitude}}$$

Including only terms up to third order :

$$HD_2 \cong \left| \frac{\frac{1}{2} a_2 V_m^2}{a_1 V_m + \frac{3}{4} a_3 V_m^3} \right| \cong \frac{1}{2} \left| \frac{a_2}{a_1} \right| V_m$$

$$HD_3 \cong \left| \frac{\frac{1}{4} a_3 V_m^3}{a_1 V_m + \frac{3}{4} a_3 V_m^3} \right| \cong \frac{1}{4} \left| \frac{a_3}{a_1} \right| V_m^2$$

- Generally the harmonic distortion is quantified in dB, taking  $20\log_{10}$  of the above ratios

# Total Harmonic Distortion

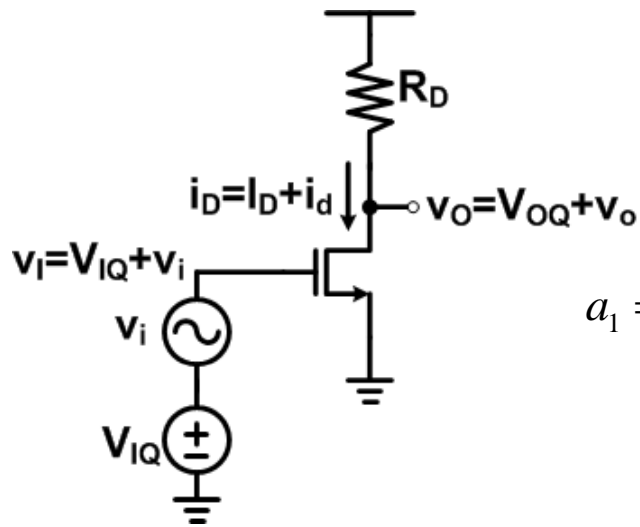
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$$THD = \frac{\text{total power of distortion signals}}{\text{fundamental signal power}}$$
$$= HD_2^2 + HD_3^2 + HD_4^2 + \dots$$

- Often dominated by the  $HD_2$  and/or  $HD_3$  term
- Typical requirements
  - High-quality audio (CD) 0.01% (-80dB)
  - Video 0.1% (-60dB)



# Common-Source Amplifier Distortion



How large can  $v_i$  be to satisfy a given THD spec?

$$i_D = \frac{1}{2} \mu C_{ox} \frac{W}{L} (V_{I_Q} + v_i - V_T)^2$$

$$a_1 = \left. \frac{\partial i_D}{\partial V_I} \right|_{V_I = V_{I_Q}} = \mu C_{ox} \frac{W}{L} (V_{I_Q} - V_T) = \mu C_{ox} \frac{W}{L} V_{ov} = \frac{2I_{DQ}}{V_{ov}} = g_m$$

$$a_2 = \left. \frac{1}{2} \frac{\partial^2 i_D}{\partial^2 V_I} \right|_{V_I = V_{I_Q}} = \frac{1}{2} \mu C_{ox} \frac{W}{L} = \frac{I_{DQ}}{V_{ov}^2}$$

$$a_3 = \left. \frac{1}{6} \frac{\partial^3 i_D}{\partial^3 V_I} \right|_{V_I = V_{I_Q}} = 0 \quad \text{higher order } a_m \text{ terms will also be zero}$$

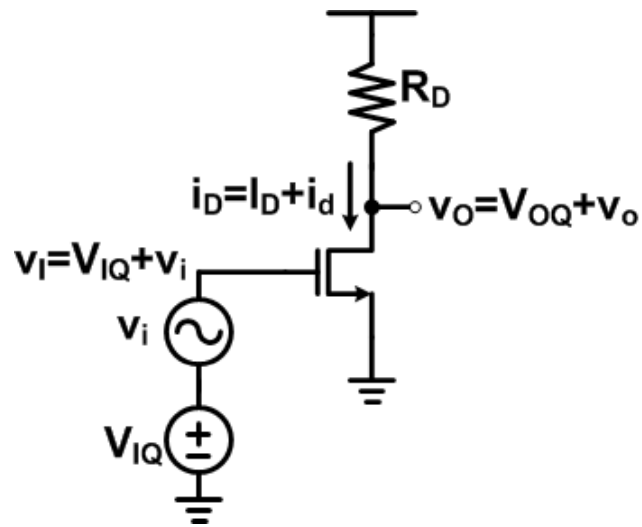
$$HD_2 \cong \frac{1}{2} \left| \frac{a_2}{a_1} \right| V_m = \frac{1}{2} \left( \frac{I_{DQ}}{V_{ov}^2} \right) \left( \frac{V_{ov}}{2I_{DQ}} \right) V_m = \frac{1}{4} \frac{V_m}{V_{ov}} \quad HD_3 \cong \frac{1}{6} \left| \frac{a_3}{a_1} \right| V_m^2 = 0$$

**For 1% (-40dB) THD :**

$$\frac{1}{4} \frac{V_m}{V_{ov}} \leq 0.01 \Rightarrow V_m \leq 0.04 V_{ov}$$

# Common-Source Amplifier Distortion

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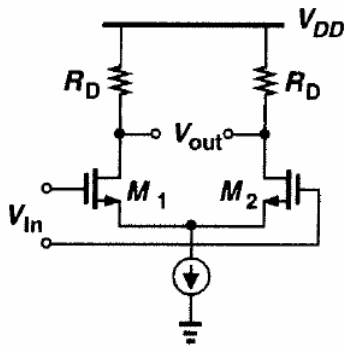
For 1% (-40dB) THD :

$$\frac{1}{4} \frac{V_m}{V_{ov}} \leq 0.01 \Rightarrow V_m \leq 0.04 V_{ov}$$

If  $V_{ov} = 1\text{V}$ , then  $V_m \leq 40\text{mV}$

- For an ideal square-law MOSFET,  $a_3$  and higher terms are zero
- However, real MOSFETs deviate from this ideal behavior and will display higher order harmonics

# Differential Pair Distortion



$$I_{D1} - I_{D2} = \mu C_{ox} \frac{W}{L} V_{OV} v_i \sqrt{1 - \frac{v_i^2}{4V_{OV}^2}} = \mu C_{ox} \frac{W}{L} V_{OV} v_i \sqrt{1 - x}$$

$$\text{where } x = \frac{v_i^2}{4V_{OV}^2}$$

Performing a Taylor Expansion w/ only 1 term

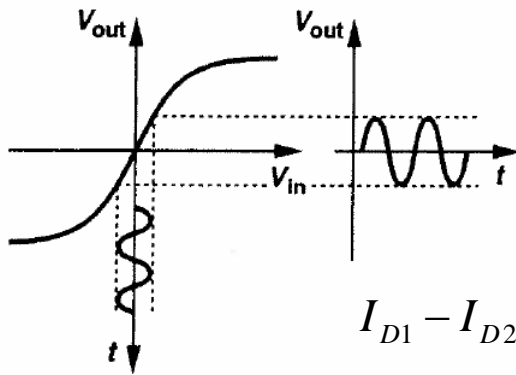
$$\sqrt{1 - x} \Rightarrow 1 - \frac{x}{2}$$

$$I_{D1} - I_{D2} \cong \mu C_{ox} \frac{W}{L} V_{OV} v_i \left[ 1 - \frac{v_i^2}{8V_{OV}^2} \right] = \mu C_{ox} \frac{W}{L} V_{OV} \left[ V_m \cos(\omega t) - \frac{V_m^3 \cos^3(\omega t)}{8V_{OV}^2} \right]$$

[Razavi]

$$I_{D1} - I_{D2} \cong g_m \left[ V_m - \frac{3V_m^2}{32V_{OV}^2} \right] \cos(\omega t) - g_m \frac{V_m^3 \cos(3\omega t)}{32V_{OV}^2}$$

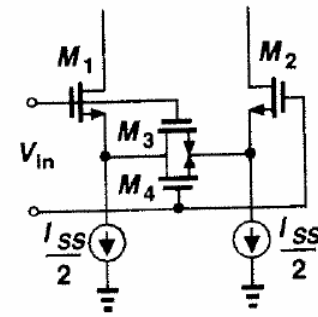
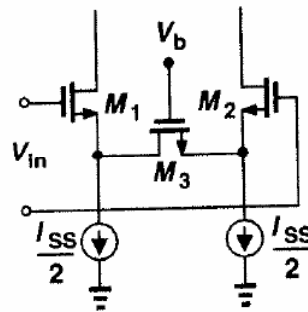
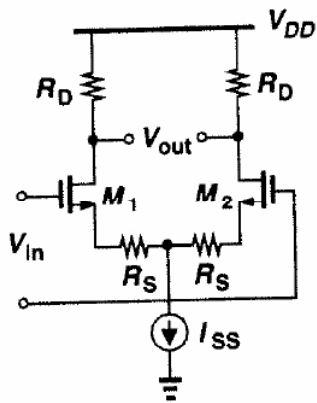
$$HD_3 = \frac{V_m^2}{32V_{OV}^2}$$



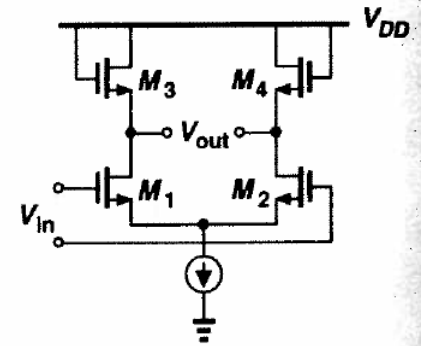
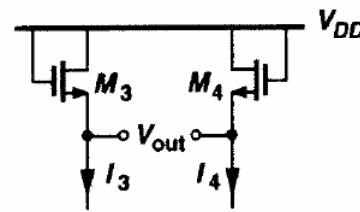
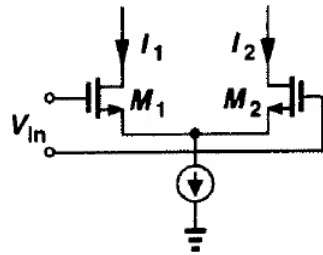
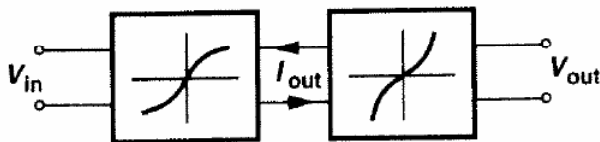
# Linearization Techniques

- Source Degeneration

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- Cascaded Nonlinear Stages



# Next Time

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- Exam 3 Review Session