

# ECEN325: Electronics

## Spring 2024

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Metal-Oxide-Semiconductor Field Effect Transistor (MOSFET)



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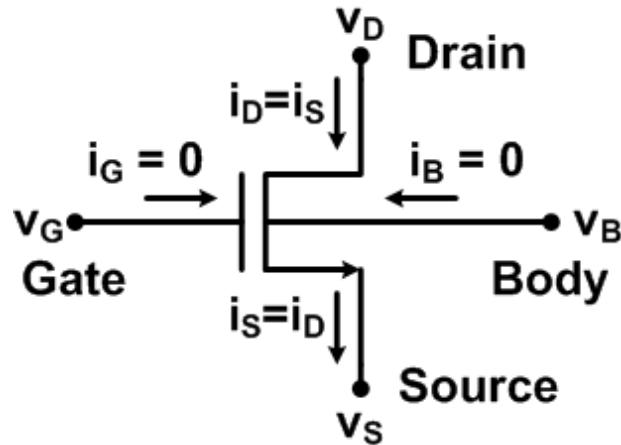
# Announcements & Reading

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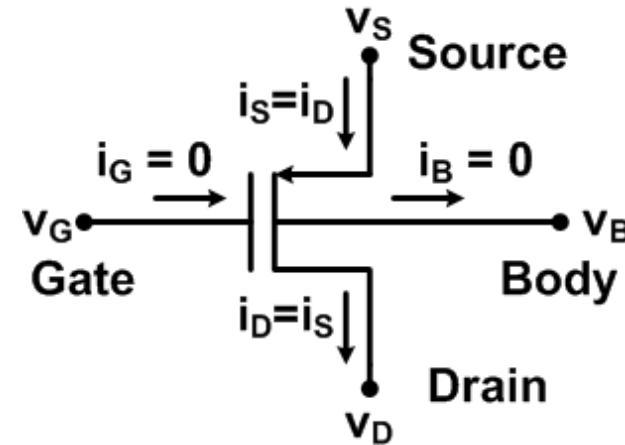
- HW 6 due Apr 25
- MOSFET Reading
  - Razavi Ch6 – MOSFET Models
  - Razavi Ch7 – MOSFET Amplifiers

# MOSFET Circuit Symbols

## NMOS



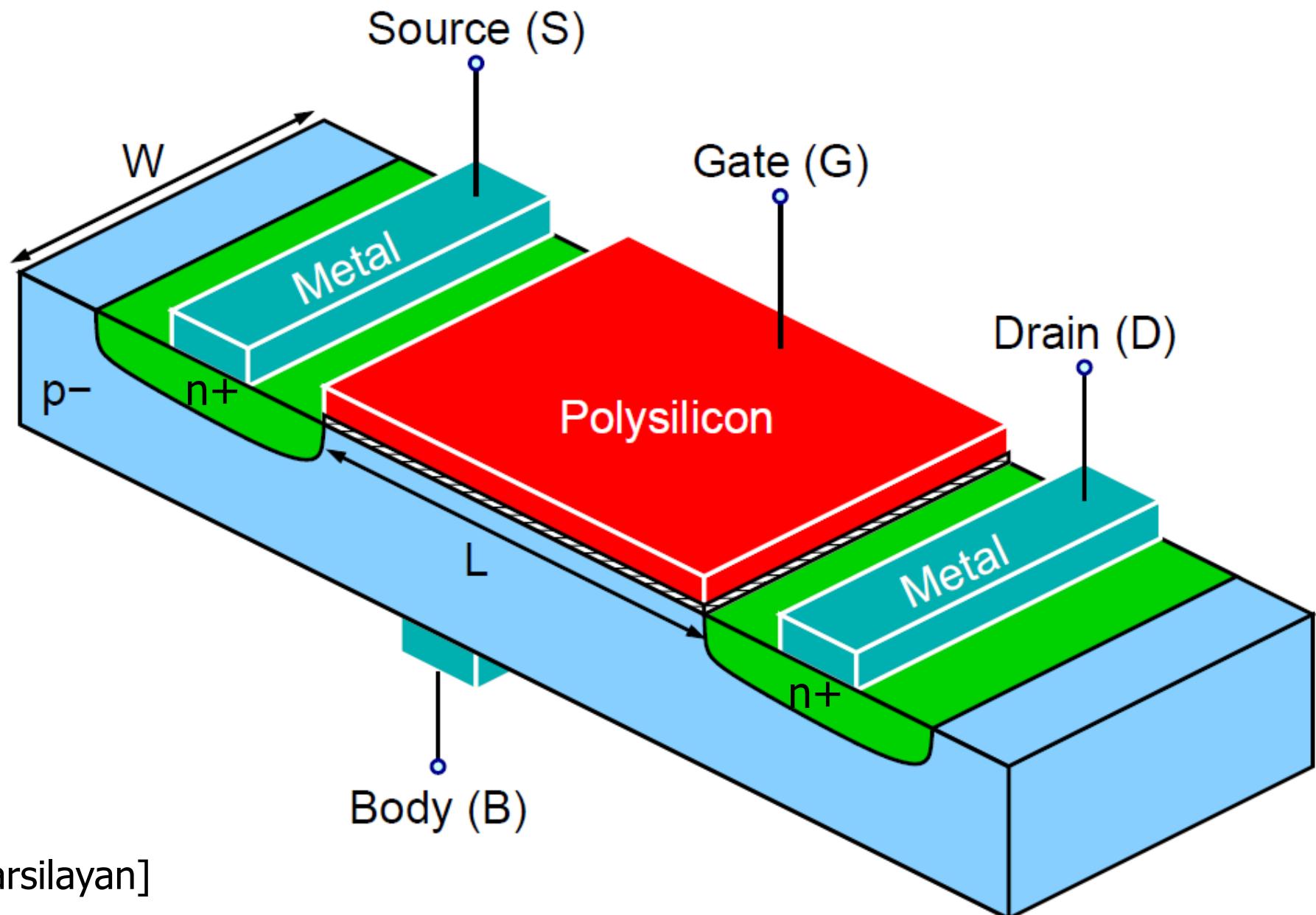
## PMOS



- MOSFETs are 4-terminal devices
  - Drain, Gate, Source, & Body
- Body terminal generally has small impact in normal operation modes, thus device is generally considered a 3-terminal device
  - Drain, Gate, and Source are respectively similar to the Collector, Base, and Emitter of the BJT
- 2 complementary MOSFETS: NMOS, PMOS

# NMOS Physical Structure

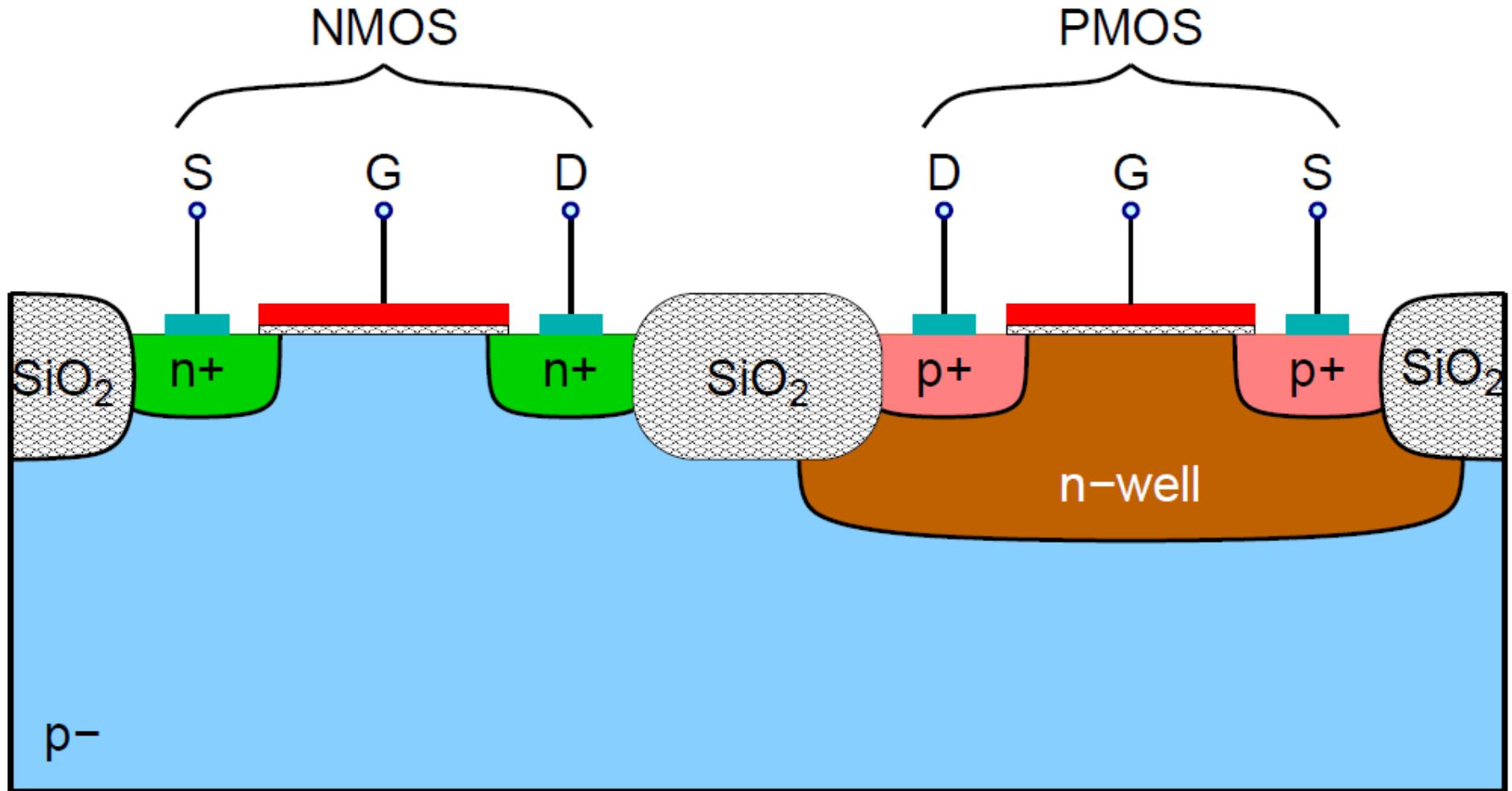
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[Karsilayan]

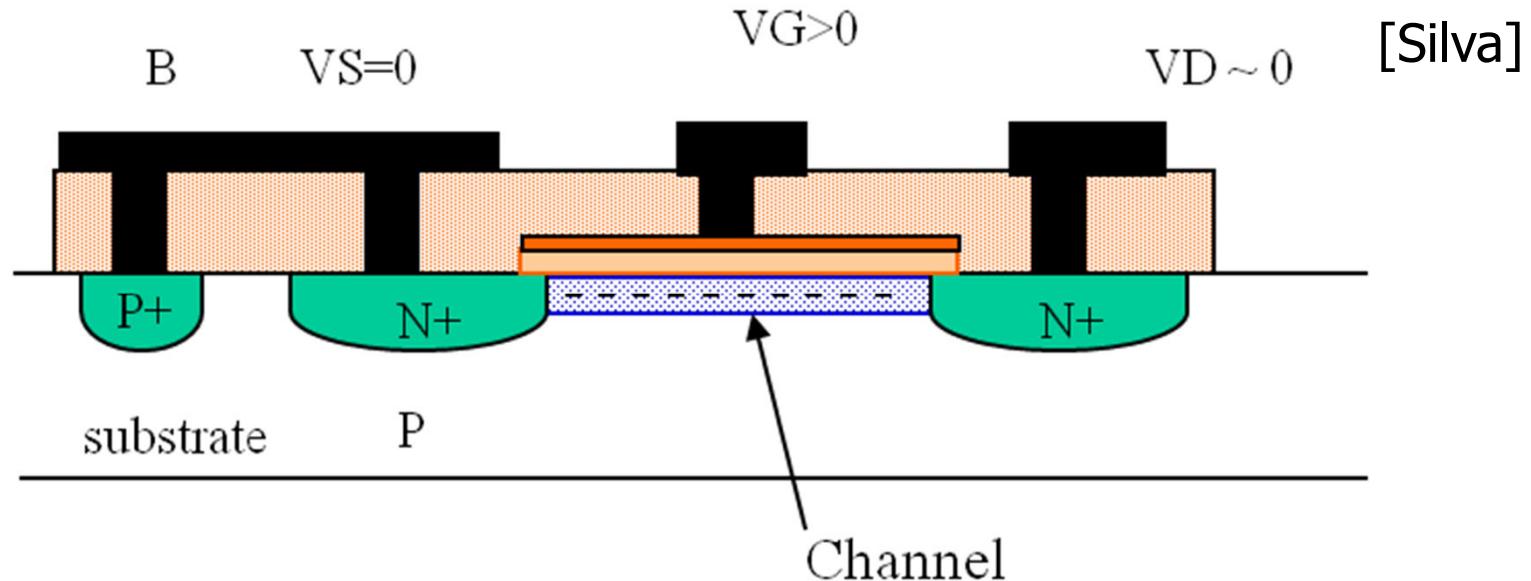
# CMOS Physical Structure

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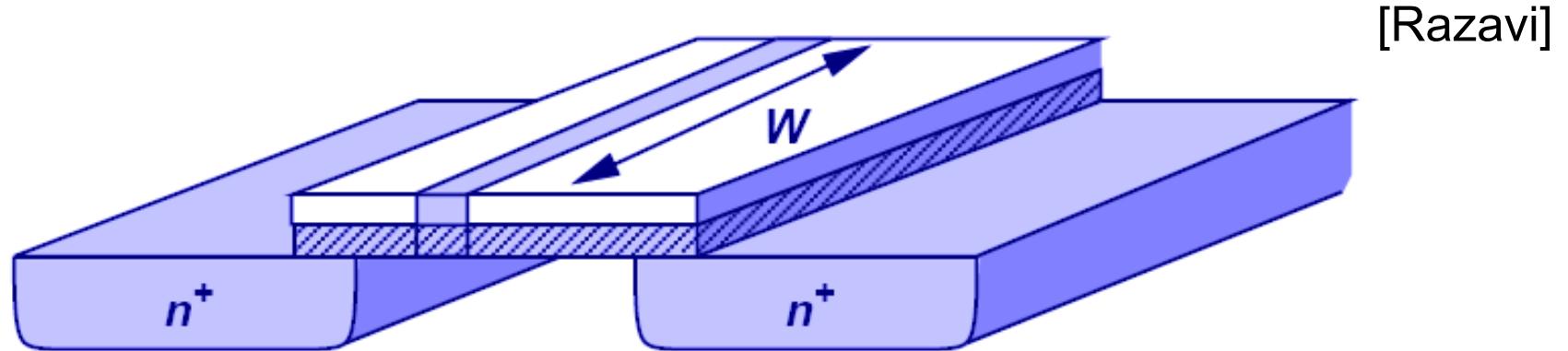
[Karsilayan]

# $V_{TH}$ Definition



- The threshold voltage,  $V_{TH}$ , is the voltage at which an “inversion layer” is formed
  - For an NMOS this is when the concentration of electrons equals the concentration of holes in the p<sup>-</sup> substrate

# Drain Current Derivation: Channel Charge Density

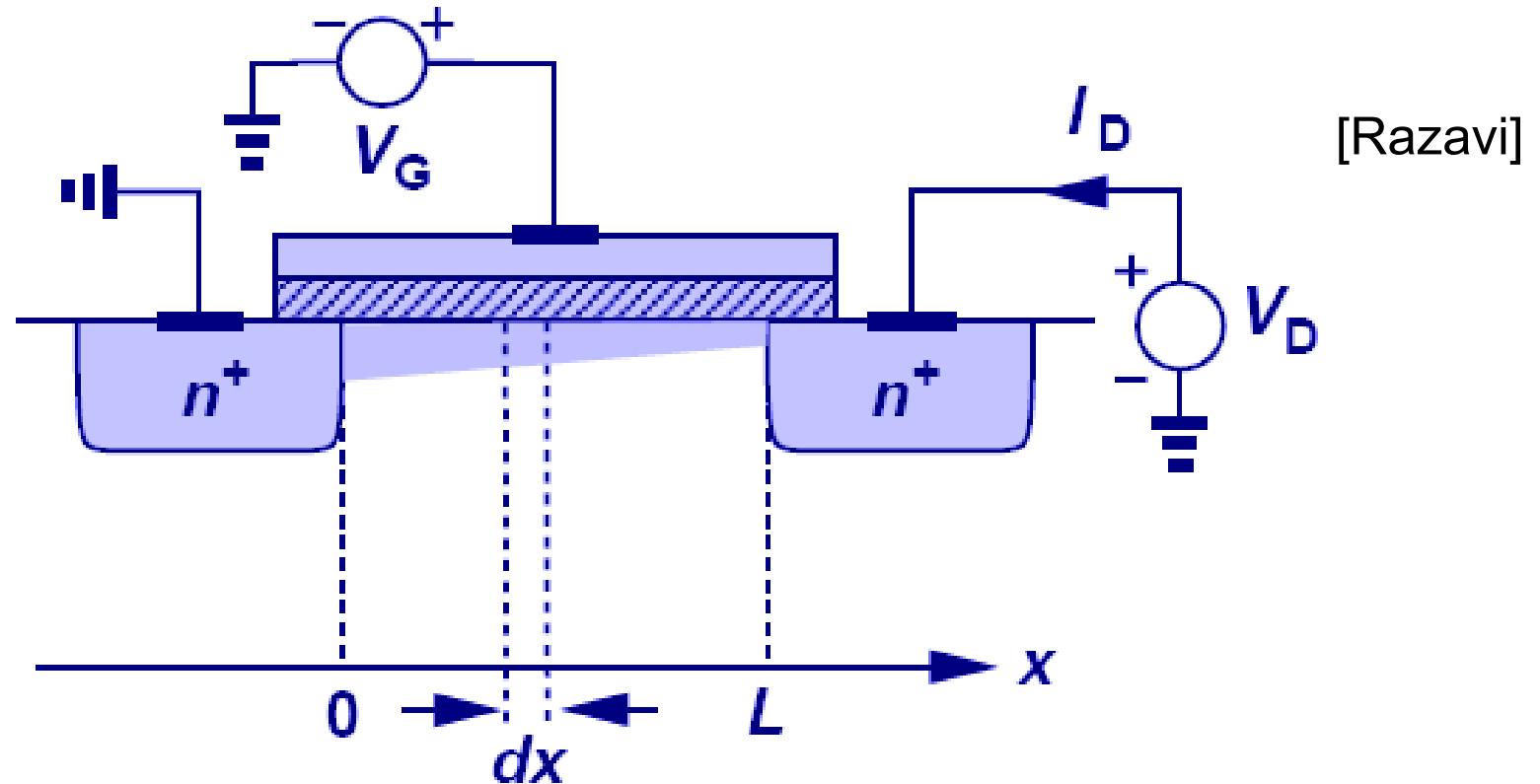


$$Q = WC_{ox}(V_{GC} - V_{TH})$$

where Capacitance per unit gate area :  $C_{ox} = \frac{\epsilon_{ox}}{t_{ox}}$

- The incremental channel charge density is equal to the gate capacitance times the gate-channel voltage in excess of the threshold voltage.

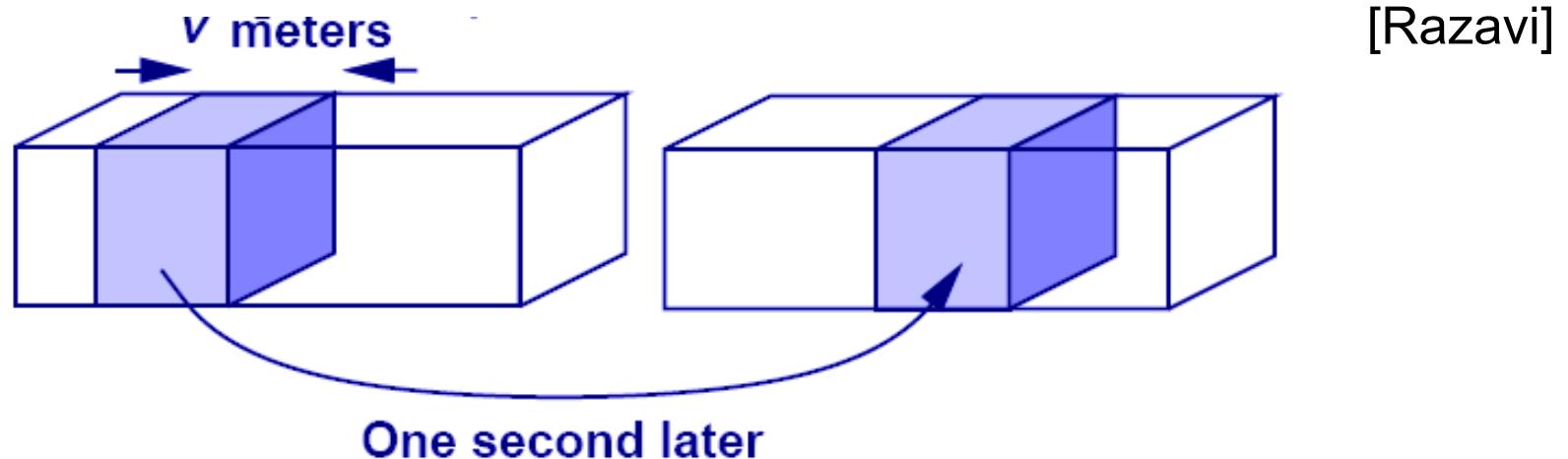
# Drain Current Derivation: Charge Density at a Point



$$Q(x) = WC_{ox} [V_{GS} - V(x) - V_{TH}]$$

- Let  $x$  be a point along the channel from source to drain, and  $V(x)$  its potential; the expression above gives the charge density (per unit length).

# Drain Current Derivation: Charge Density and Current

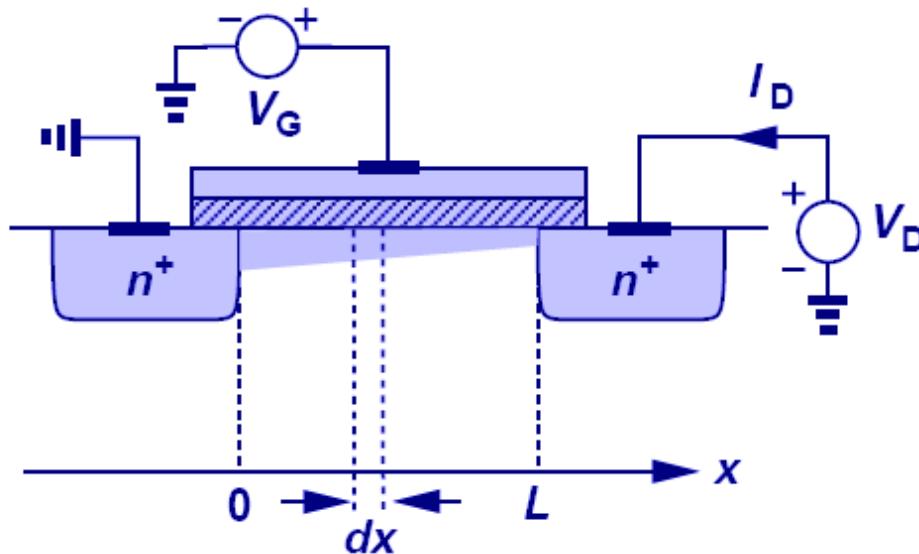


[Razavi]

$$I = Q \cdot v$$

- The current that flows from source to drain (electrons) is related to the charge density in the channel by the charge velocity.

# Drain Current Derivation: Triode Region (Small $V_{DS}$ ) Current Equation



[Razavi]

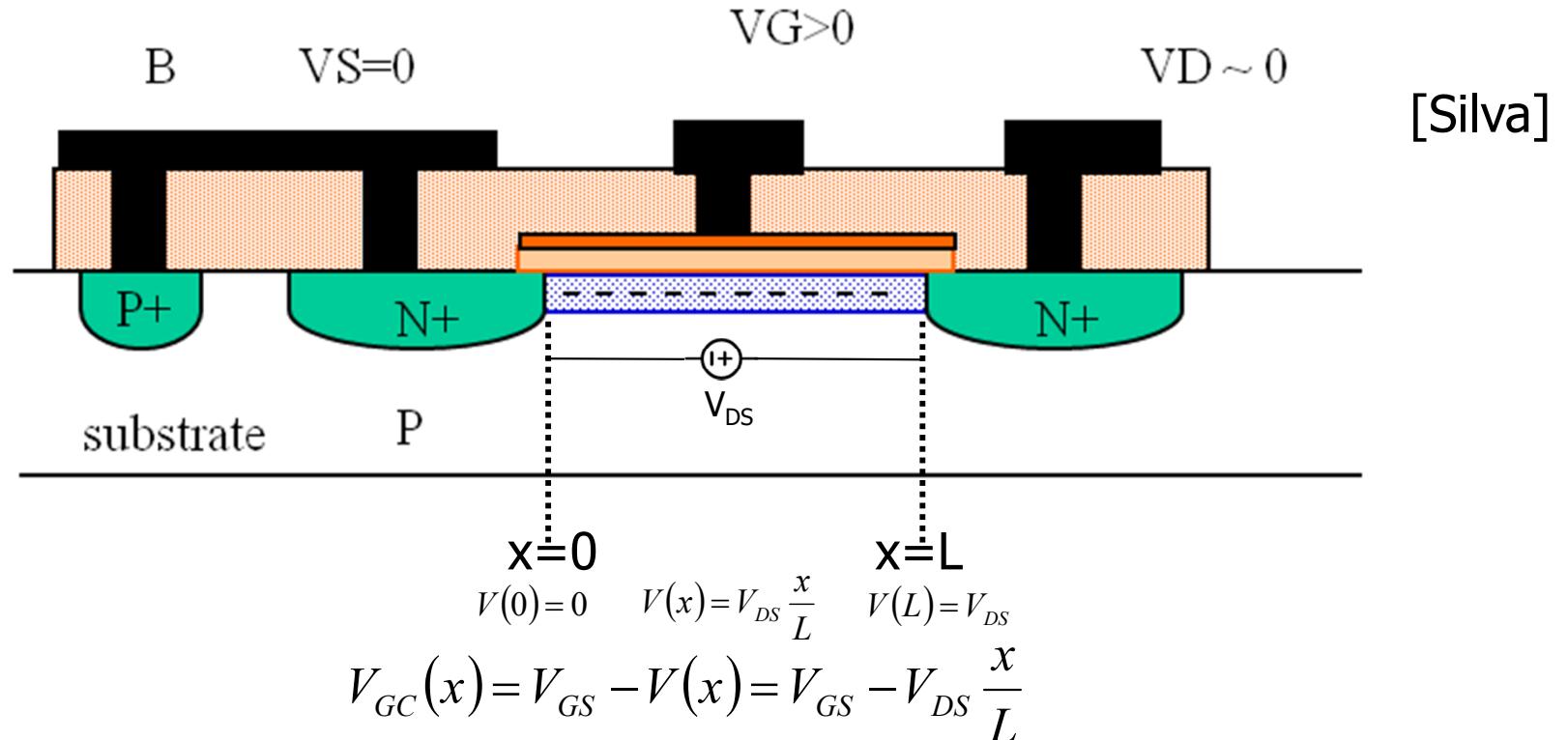
Electron Velocity:  $v = +\mu_n \frac{dV}{dx}$

$$I_D = Q(x)v = WC_{ox}[V_{GS} - V(x) - V_{TH}] \mu_n \frac{dV(x)}{dx}$$

$$\int_{x=0}^{x=L} I_D dx = \int_{V(x)=0}^{V(x)=V_{DS}} \mu_n C_{ox} W [V_{GS} - V(x) - V_{TH}] dV(x)$$

$$I_D = \mu_n C_{ox} \frac{W}{L} \left[ V_{GS} - V_{TH} - \frac{1}{2} V_{DS} \right] V_{DS}$$

# Triode or Linear Region



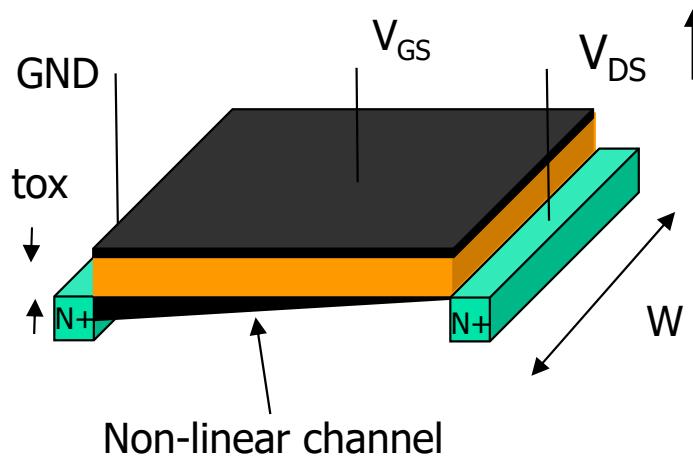
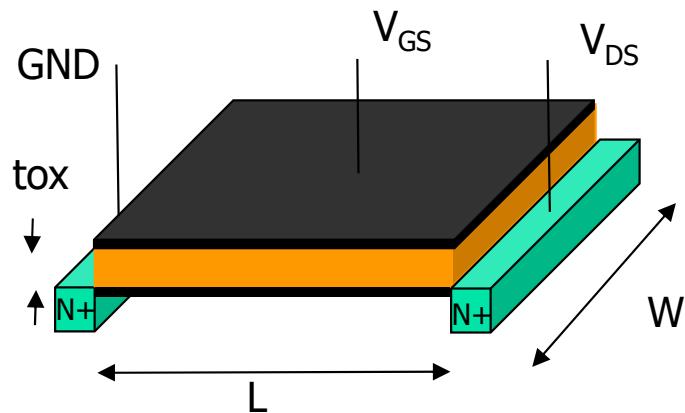
- Channel depth and transistor current is a function of the overdrive voltage,  $V_{GS}-V_T$ , and  $V_{DS}$
- Because  $V_{DS}$  is small,  $V_{GC}$  is roughly constant across channel length and channel depth is roughly uniform

$$I_{DS} = \frac{W}{L} \mu_n C_{ox} (V_{GS} - V_{Tn} - 0.5V_{DS}) V_{DS}$$

For small  $V_{DS}$

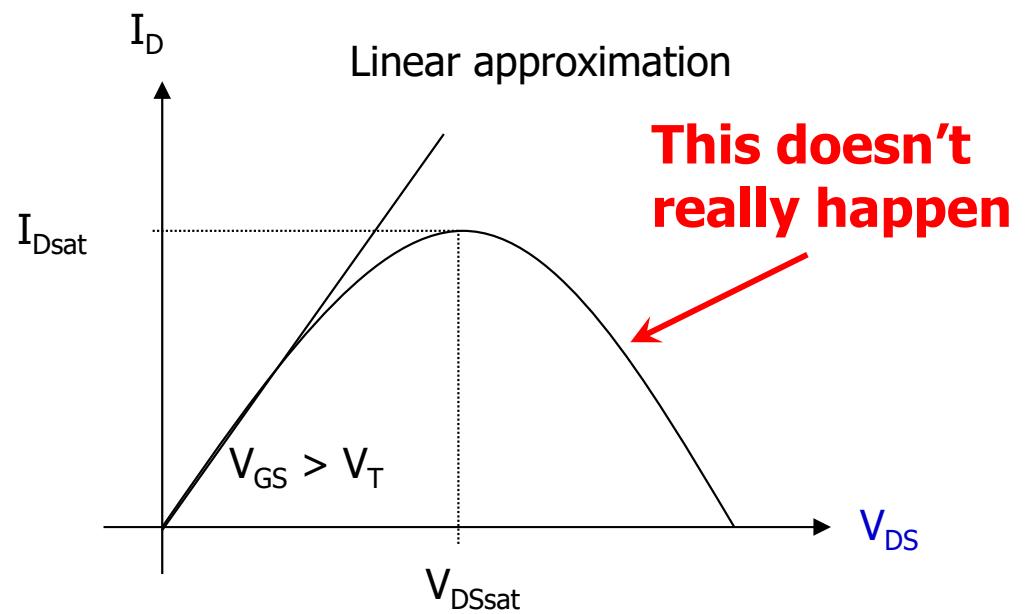
$$R_{DS} \approx \frac{1}{\frac{W}{L} \mu C_{ox} (V_{GS} - V_{Tn})}$$

# MOS Equations in Triode Region (Large $V_{DS}$ )



Drain current: Expression used in SPICE level 1

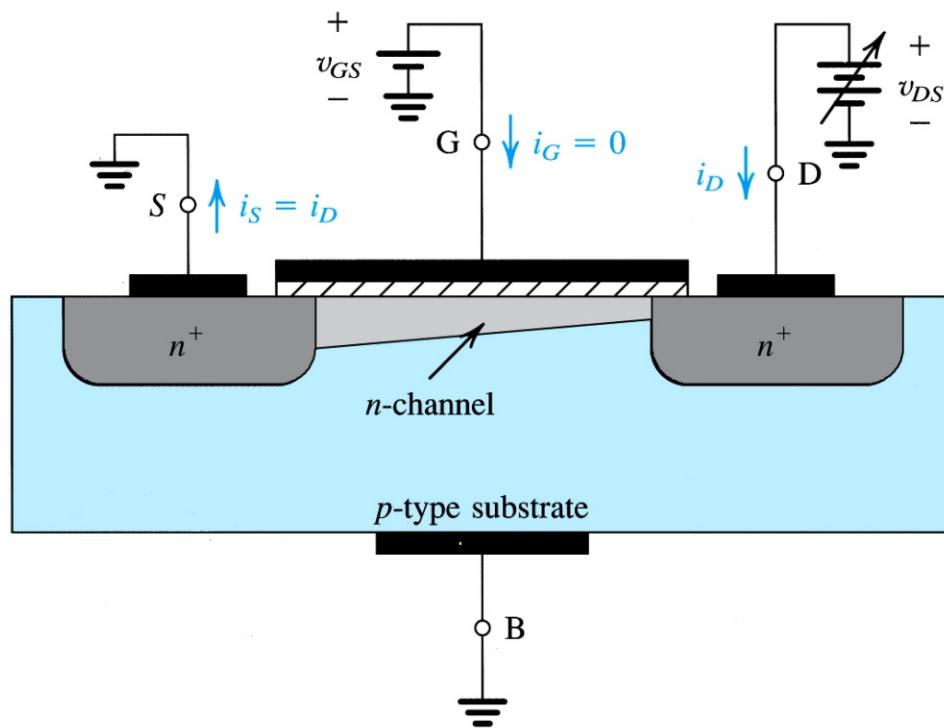
$$I_{DS} = \frac{W}{L} \mu_n C_{OX} (V_{GS} - V_{Tn} - 0.5V_{DS}) V_{DS}$$



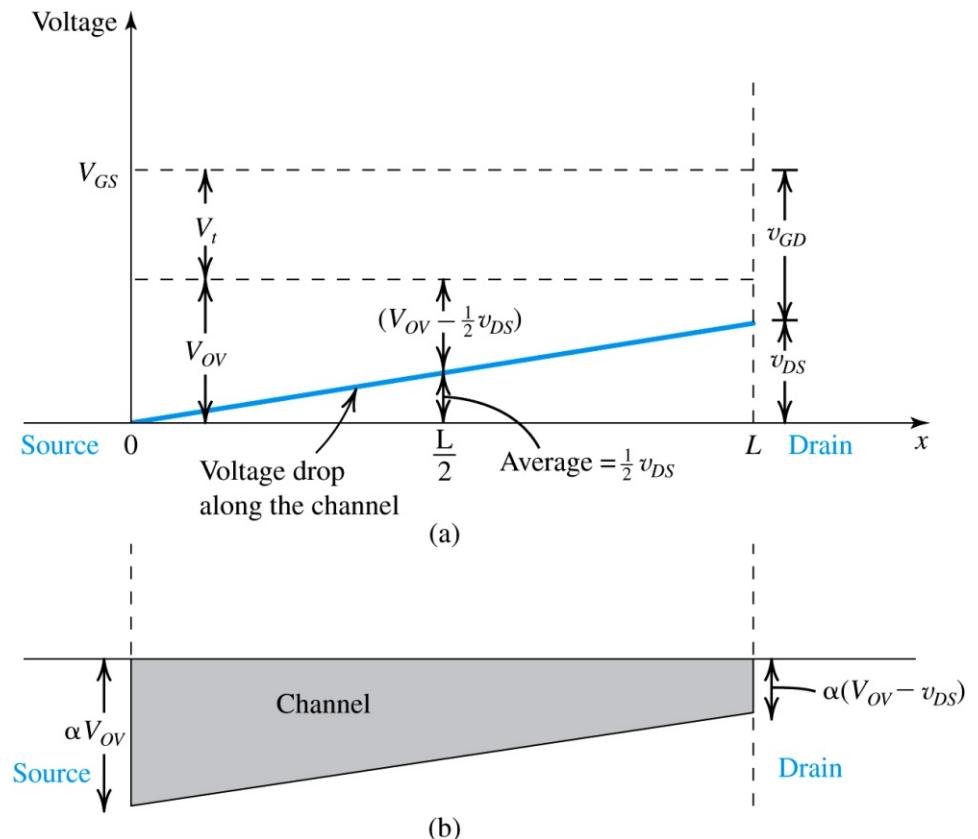
$$V_{DSsat} = V_{GS} - V_{Tn}$$

# Triode Region Channel Profile

[Sedra/Smith]

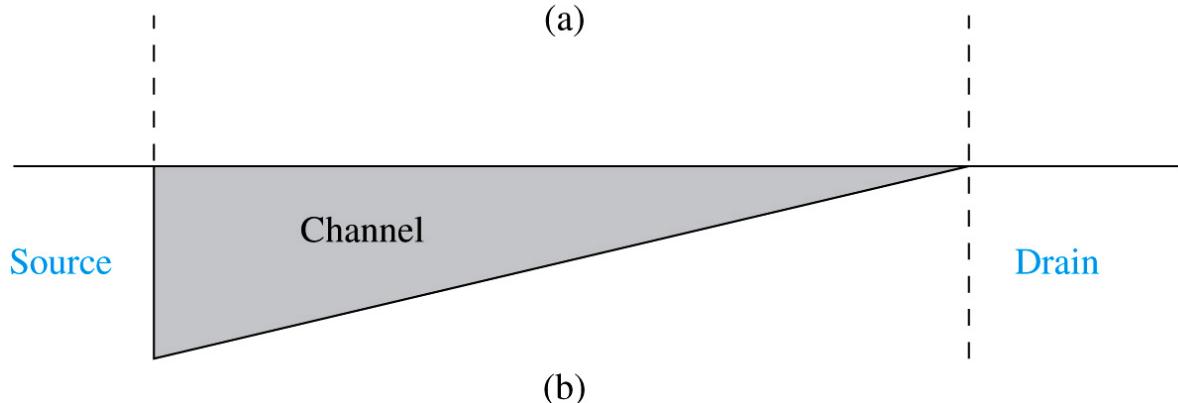
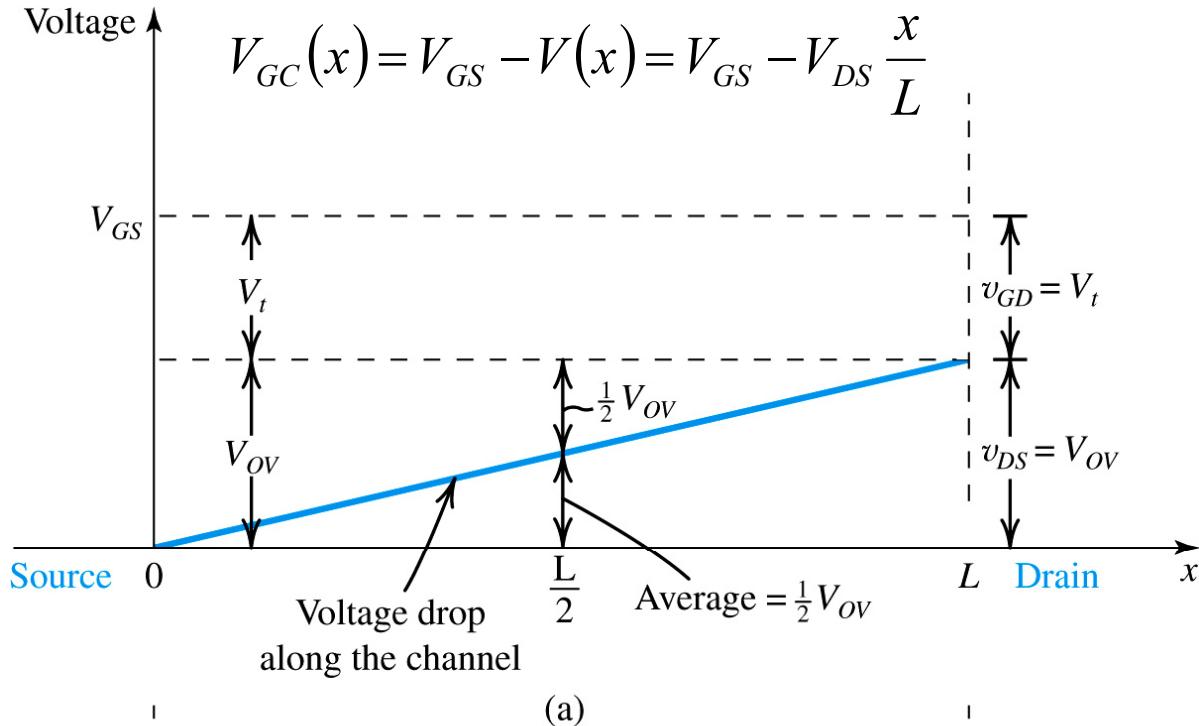


$$V_{GC}(x) = V_{GS} - V(x) = V_{GS} - V_{DS} \frac{x}{L}$$



- If  $V_{GC}$  is always above  $V_T$  throughout the channel length, the transistor current obeys the triode region current equation

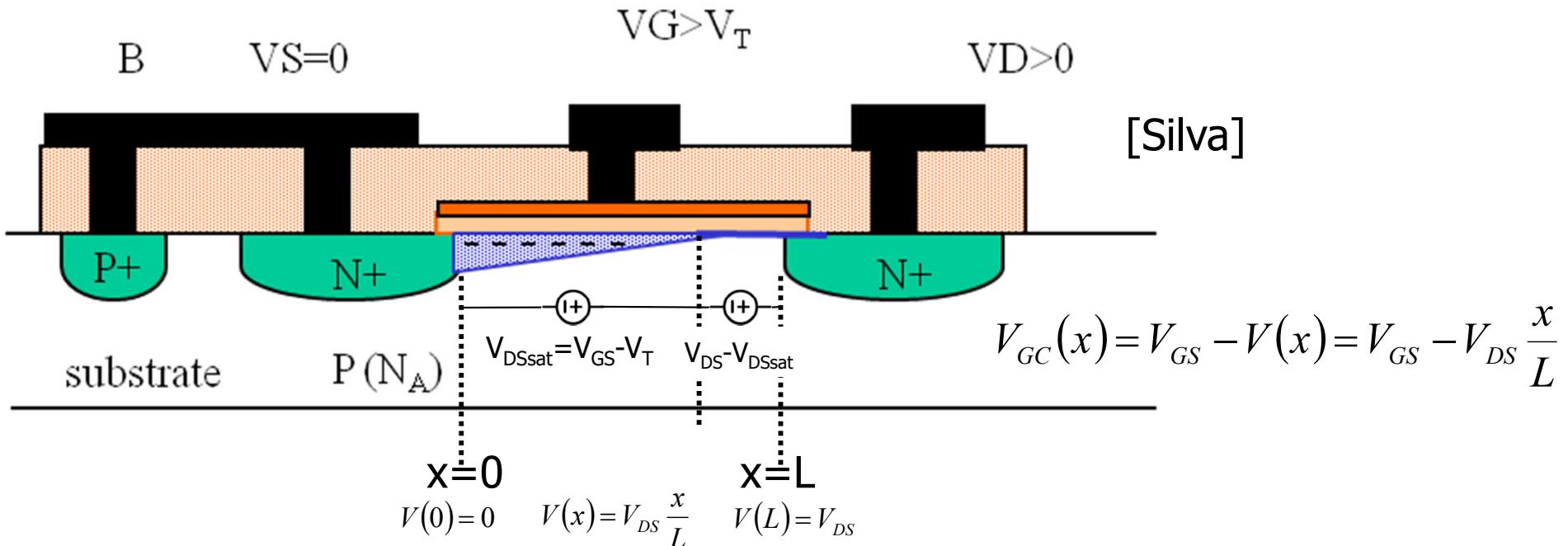
# Saturation Region Channel Profile



[Sedra/Smith]

- When  $V_{DS} \geq V_{GS} - V_{TH} = V_{OV}$ ,  $V_{GC}$  no longer exceeds  $V_{TH}$ , resulting in the channel “pinching off” and the current saturating to a value that is no longer a function of  $V_{DS}$  (ideally)

# Saturation Region



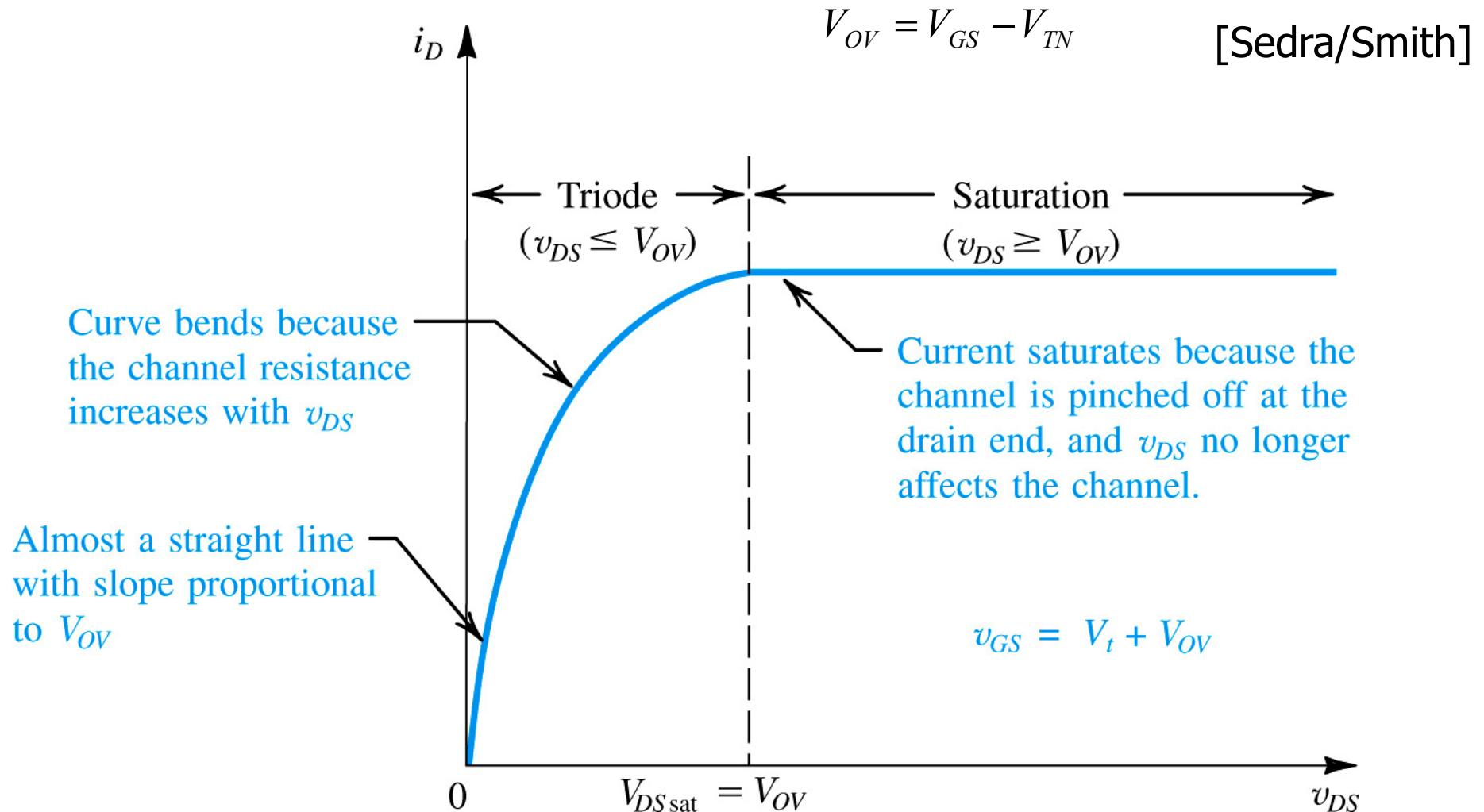
- Channel “pinches-off” when  $V_{DS}=V_{GS}-V_{TH}$  and the current saturates
- After channel charge goes to 0, the high lateral field “sweeps” the carriers to the drain and drops the extra  $V_{DS}$  voltage

$$I_{DS} = \mu_n C_{OX} \frac{W}{L} \left( V_{GS} - V_{Tn} - \frac{V_{DS}}{2} \right) V_{DS} \Bigg|_{V_{DS} = V_{GS} - V_{Tn}}$$

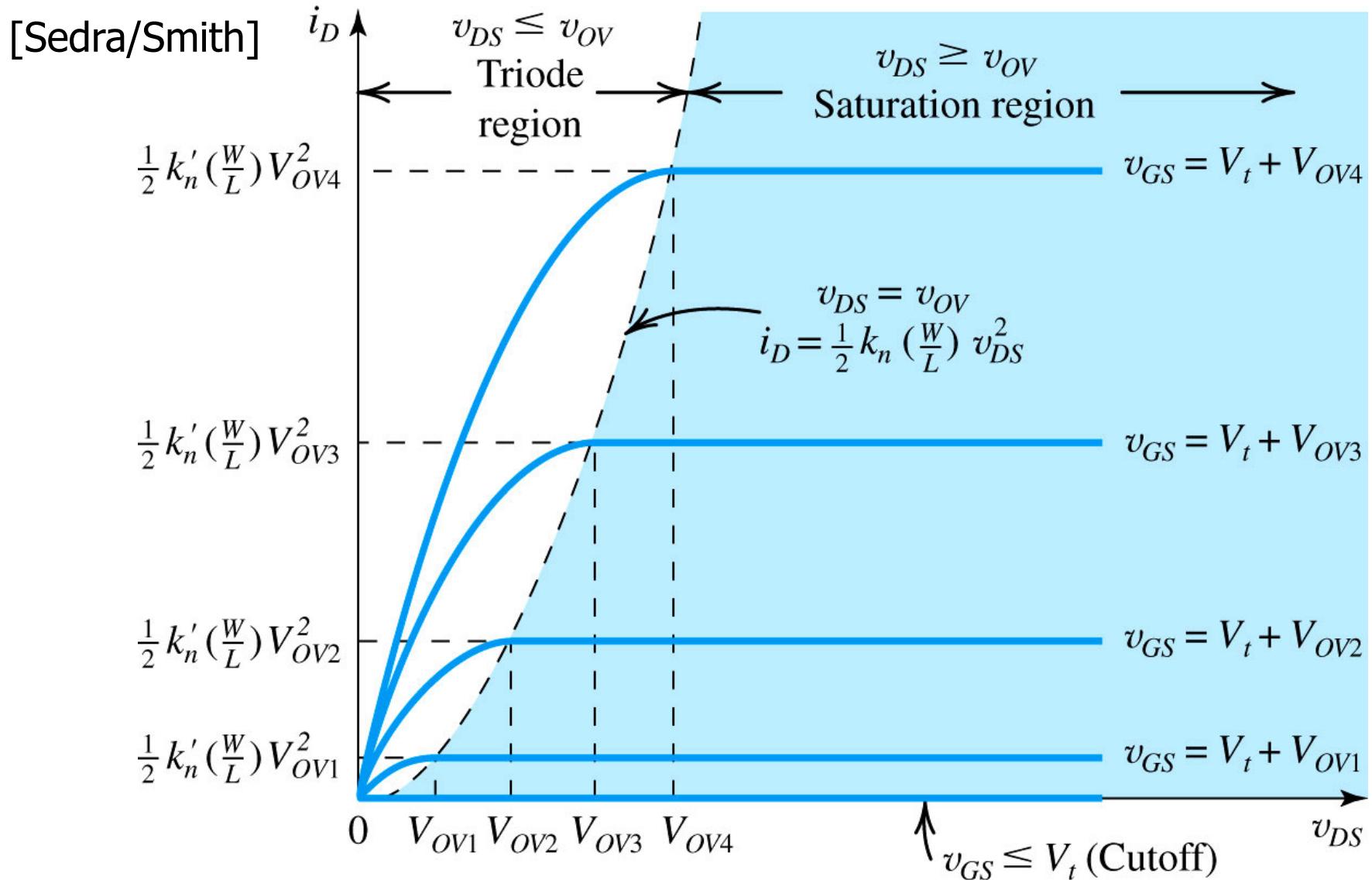
$$V_{DSsat} = V_{GS} - V_{Tn}$$

$$I_{DS} = \frac{\mu_n C_{OX}}{2} \frac{W}{L} (V_{GS} - V_{Tn})^2$$

# NMOS $I_D$ – $V_{DS}$ Characteristics

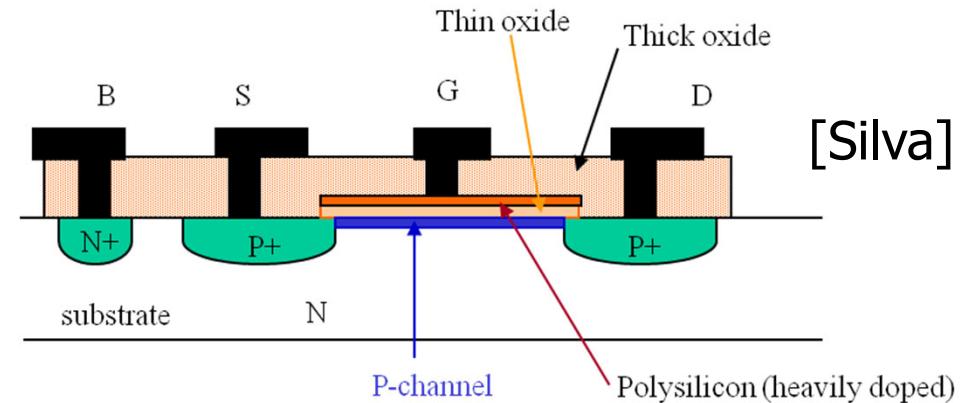
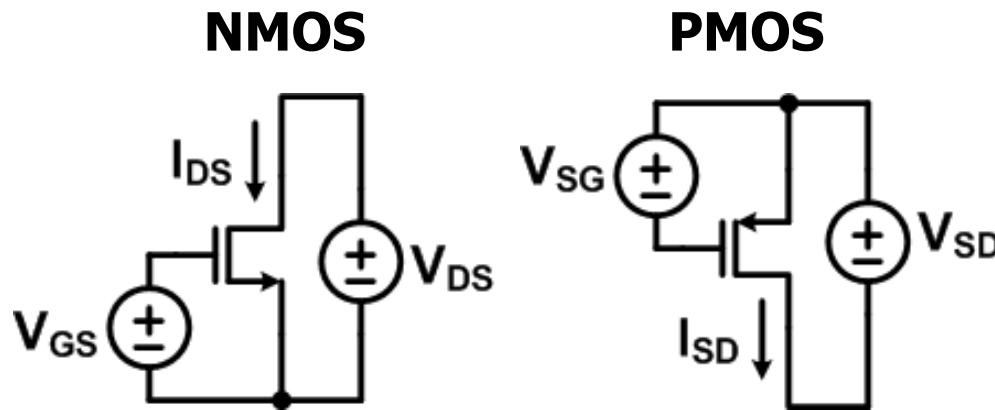


# MOS “Large-Signal” Output Characteristic



**Note:**  $V_{ov} = V_{GS} - V_T$

# What about the PMOS device?



- The current equations for the PMOS device are the same as the NMOS **EXCEPT** you swap the current direction and all the voltage polarities

**NMOS**

$$\text{Linear: } I_{DS} = \frac{W}{L} \mu_n C_{OX} (V_{GS} - V_{Tn} - 0.5V_{DS}) V_{DS}$$

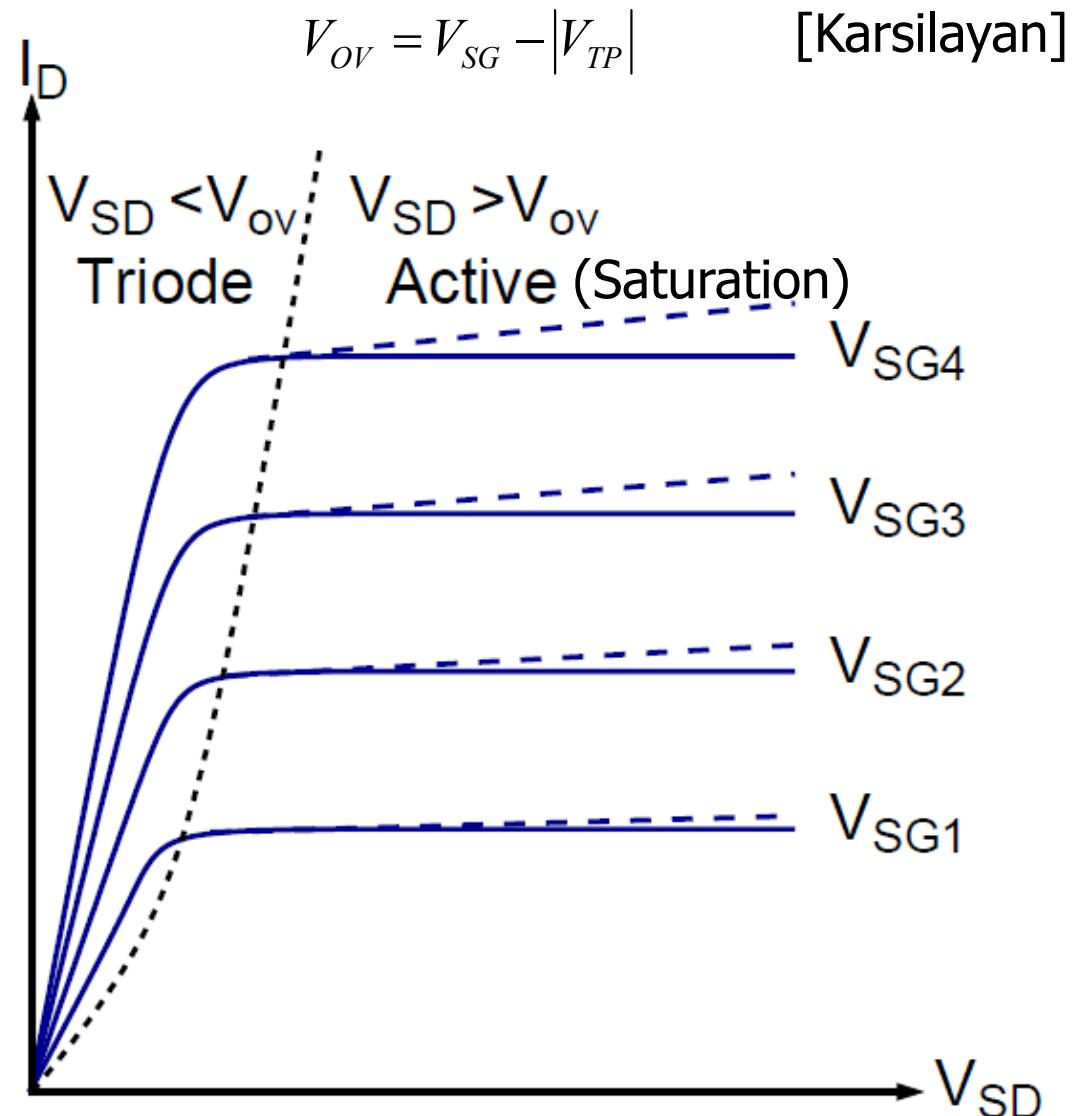
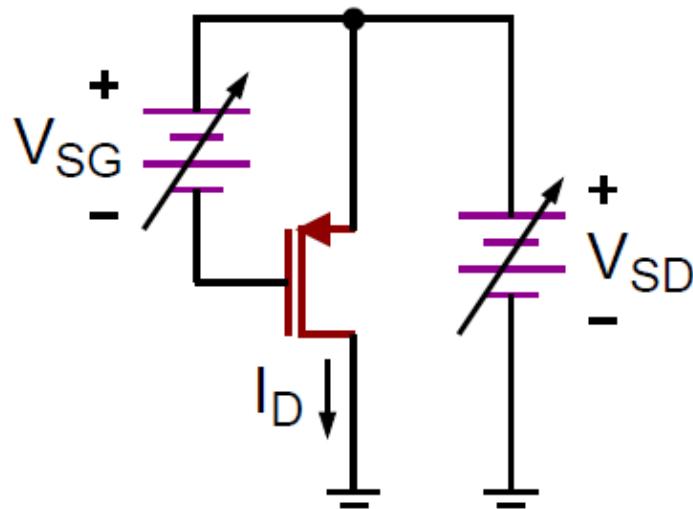
$$\text{Saturation: } I_{DS} = \frac{W}{2L} \mu_n C_{OX} (V_{GS} - V_{Tn})^2$$

**PMOS**

$$I_{SD} = \frac{W}{L} \mu_p C_{OX} (V_{SG} - |V_{Tp}| - 0.5V_{SD}) V_{SD}$$

$$I_{SD} = \frac{W}{2L} \mu_p C_{OX} (V_{SG} - |V_{Tp}|)^2$$

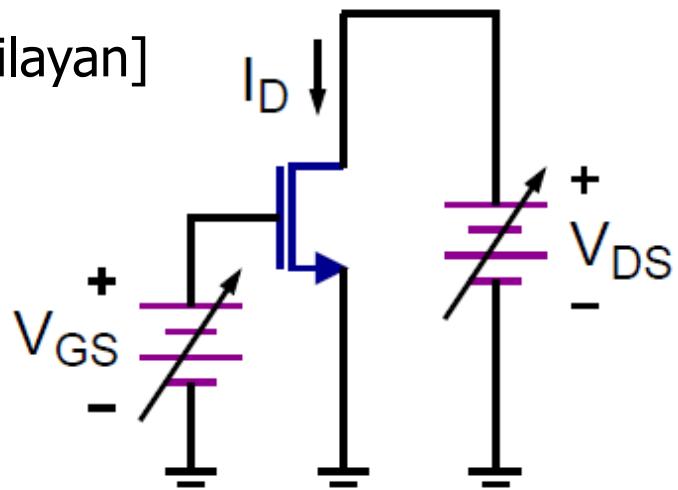
# PMOS $I_D$ – $V_{SD}$ Characteristics



# NMOS DC Operation (w/ infinite $r_{out}$ )

Region	Bias Condition	$I_{DS}$
Cutoff	$V_{GS} < V_{TN}$	$I_{DS} = 0$
Triode (Linear)	$V_{GS} > V_{TN}, V_{DS} < V_{GS} - V_{TN}$	$I_{DS} = \mu_n C_{ox} \frac{W}{L} \left( V_{GS} - V_{TN} - \frac{V_{DS}}{2} \right) V_{DS}$
Saturation (Active)	$V_{GS} > V_{TN}, V_{DS} > V_{GS} - V_{TN}$	$I_{DS} = \frac{\mu_n C_{ox}}{2} \frac{W}{L} (V_{GS} - V_{TN})^2$

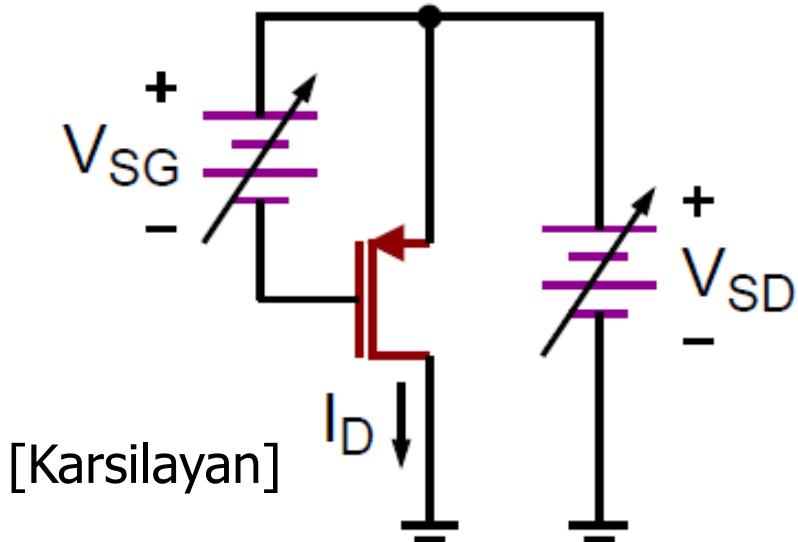
[Karsilayan]



- In transistor model, often combine  $\mu_n C_{ox}$  term as a parameter  $KP_N$  with units  $A/V^2$
- In lab, we combine  $\mu_n C_{ox}(W/L)$  term as a parameter  $\beta_N$  with units  $A/V^2$

# PMOS DC Operation (w/ infinite $r_{out}$ )

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Cutoff	$V_{SG} <  V_{TP} $	$I_{SD} = 0$
Triode (Linear)	$V_{SG} >  V_{TP} , V_{SD} < V_{SG} -  V_{TP} $	$I_{SD} = \mu_p C_{ox} \frac{W}{L} \left( V_{SG} -  V_{TP}  - \frac{V_{SD}}{2} \right) V_{SD}$
Saturation (Active)	$V_{SG} >  V_{TP} , V_{SD} > V_{SG} -  V_{TP} $	$I_{SD} = \frac{\mu_p C_{ox}}{2} \frac{W}{L} \left( V_{SG} -  V_{TP}  \right)^2$



- In transistor model, often combine  $\mu_p C_{ox}$  term as a parameter  $KP_P$  with units  $A/V^2$
- In lab, we combine  $\mu_p C_{ox}(W/L)$  term as a parameter  $\beta_P$  with units  $A/V^2$