

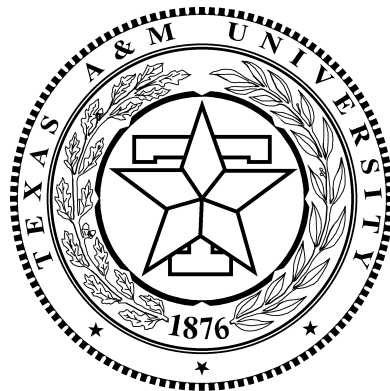
ECEN 326

Electronic Circuits

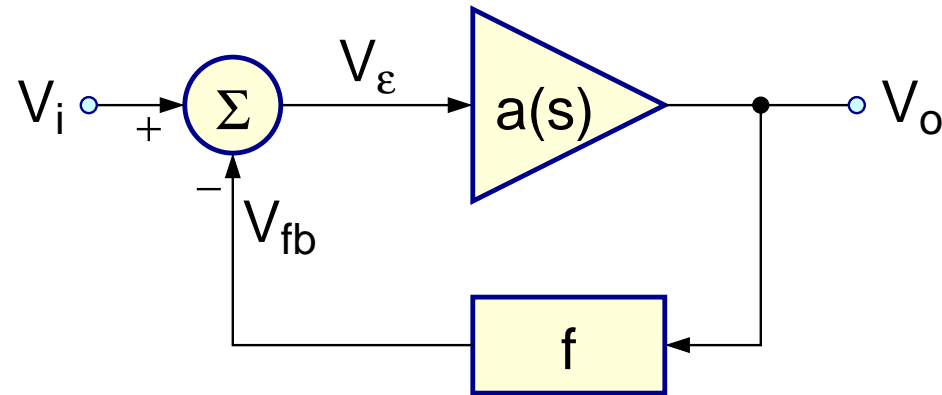
Stability

Dr. Aydın İlker Karşılayan

Texas A&M University
Department of Electrical and Computer Engineering



Ideal Configuration

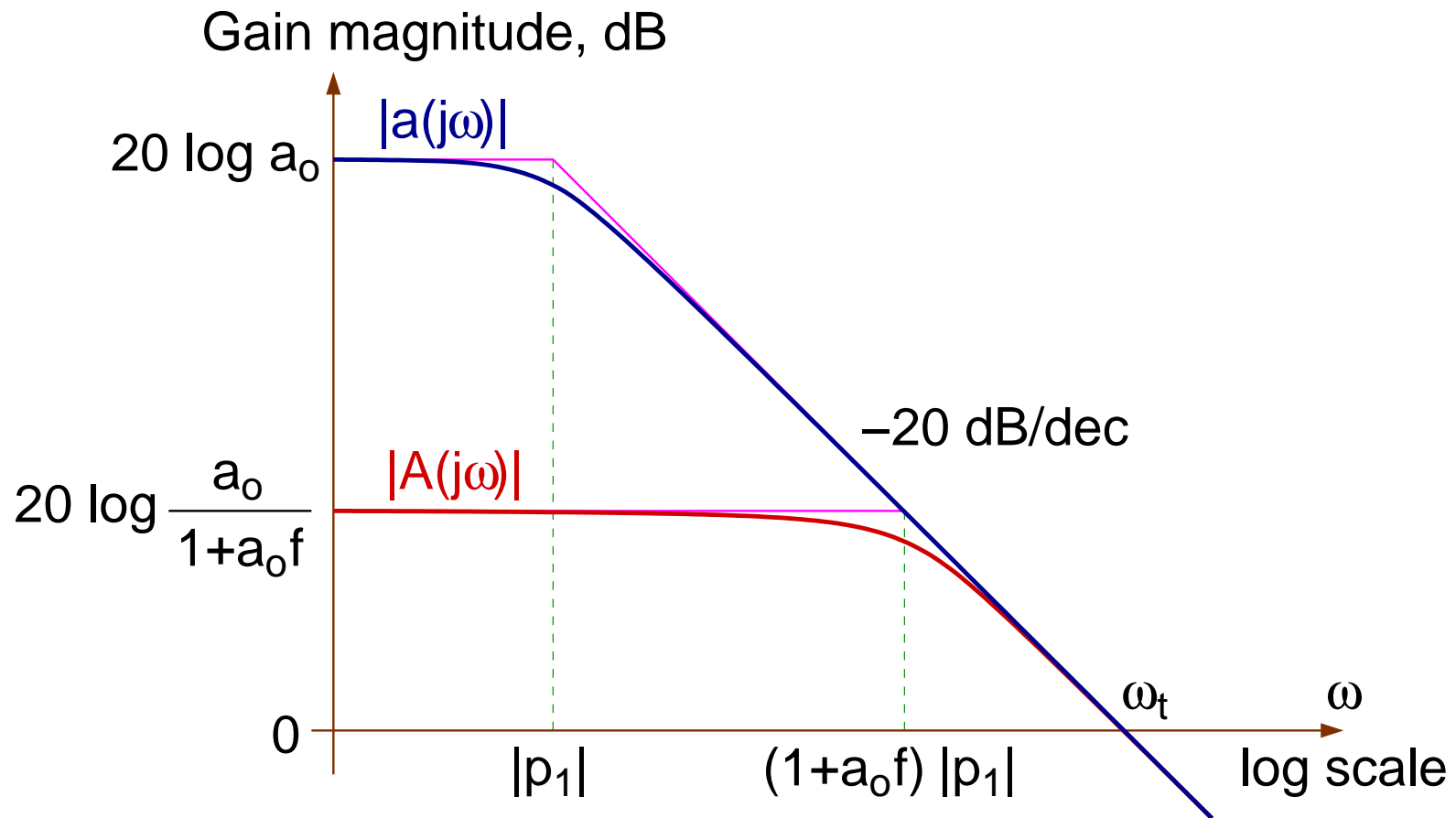


$$a(s) = \frac{V_o}{V_\epsilon}(s) = \frac{a_o}{1 - \frac{s}{p_1}}$$

$$A(s) = \frac{V_o}{V_i}(s) = \frac{a(s)}{1 + a(s)f} = \frac{\frac{a_o}{1 + \frac{a_o f s}{1 + a_o f}}}{1 - \frac{a_o}{(1 + a_o f)p_1}}$$

Gain-Bandwidth

1-pole amplifier



Instability and the Nyquist Criterion

Transfer function of a 3-pole amplifier:

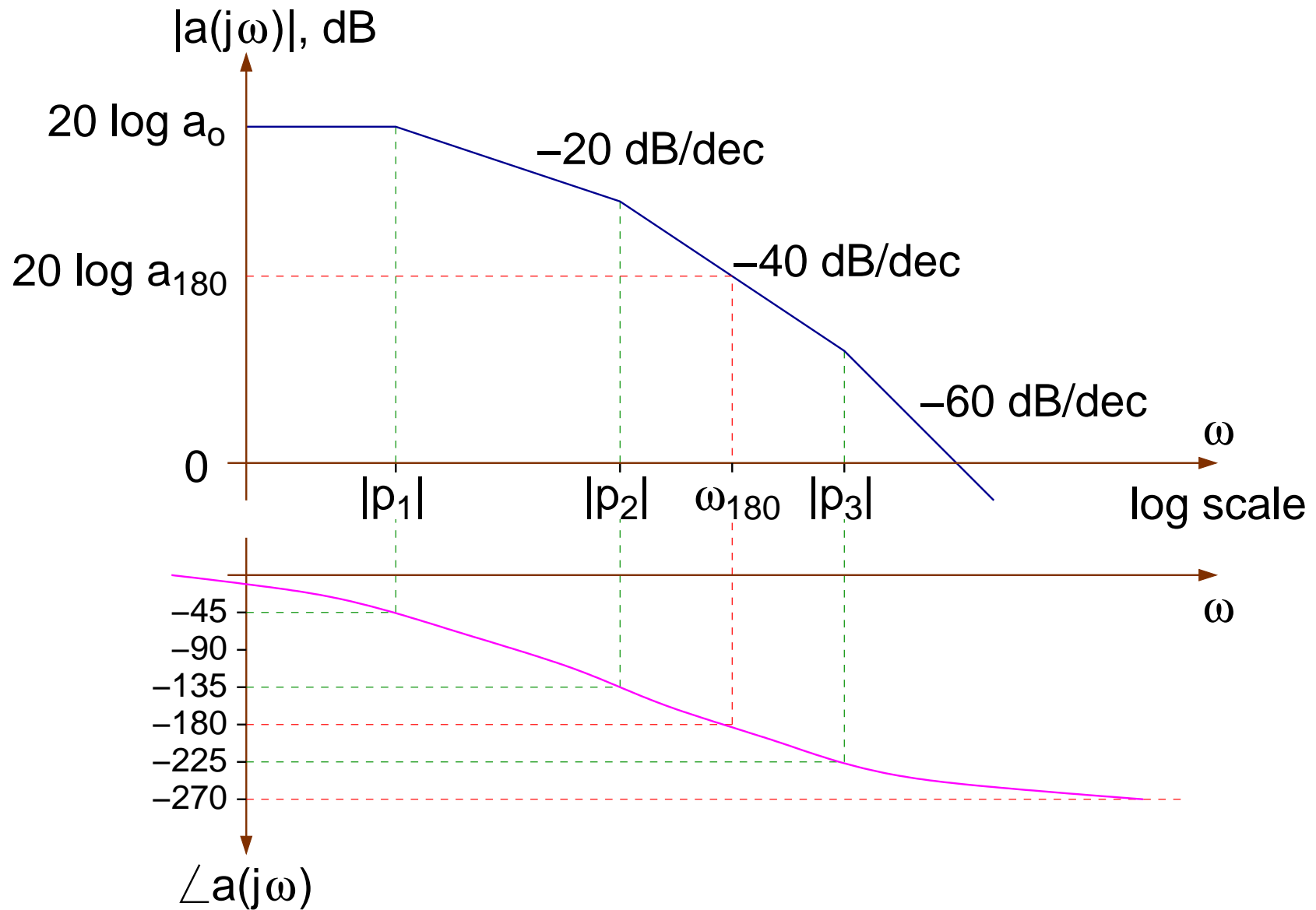
$$a(s) = \frac{a_o}{\left(1 - \frac{s}{p_1}\right) \left(1 - \frac{s}{p_2}\right) \left(1 - \frac{s}{p_3}\right)}$$

Nyquist criterion for stability of the amplifier:

Consider a feedback amplifier with a stable $\mathbf{T}(s)$. If the Nyquist plot of $\mathbf{T}(j\omega)$ encircles the point $(-1,0)$, the feedback amplifier is unstable.

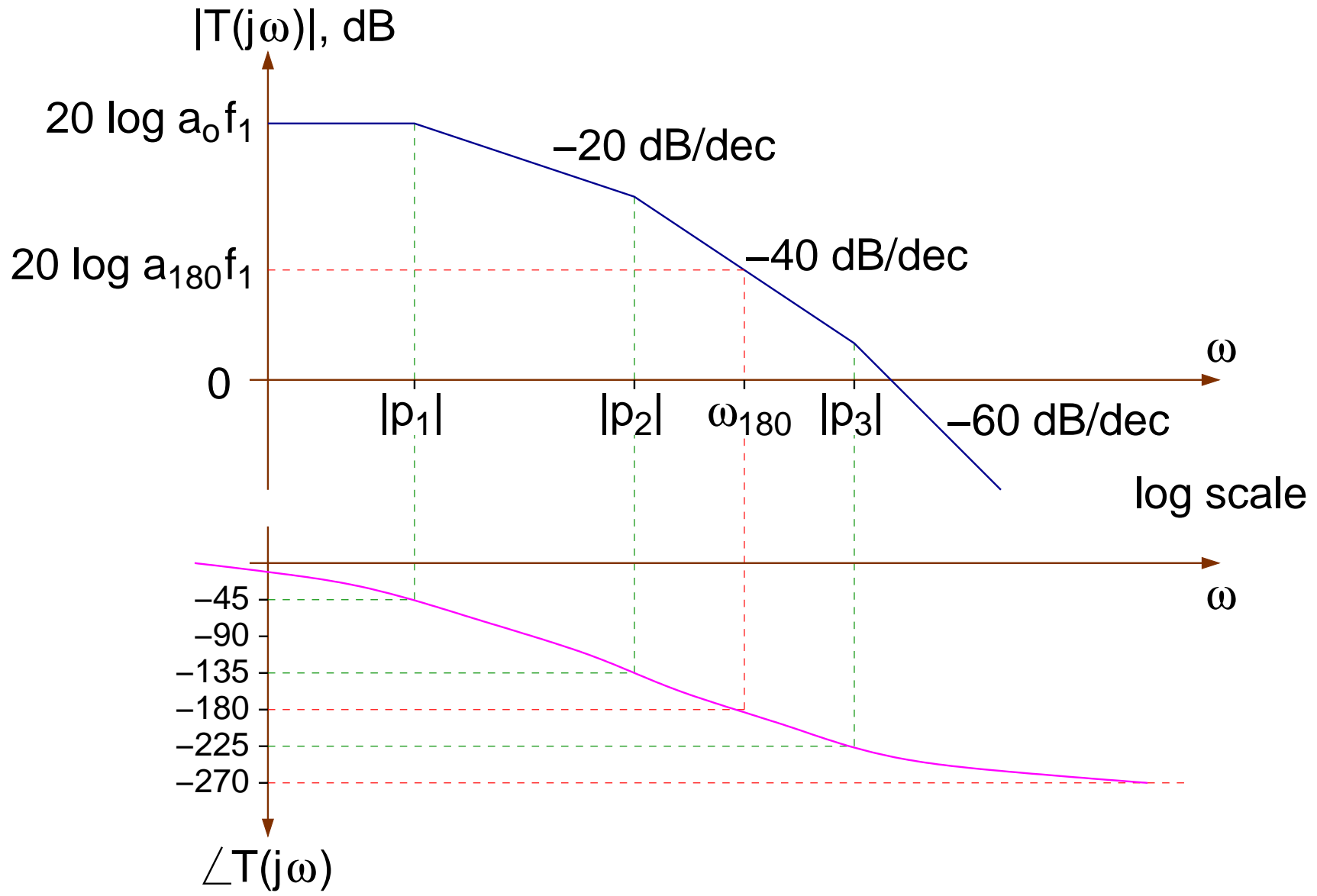
Magnitude & Phase

3-pole amplifier



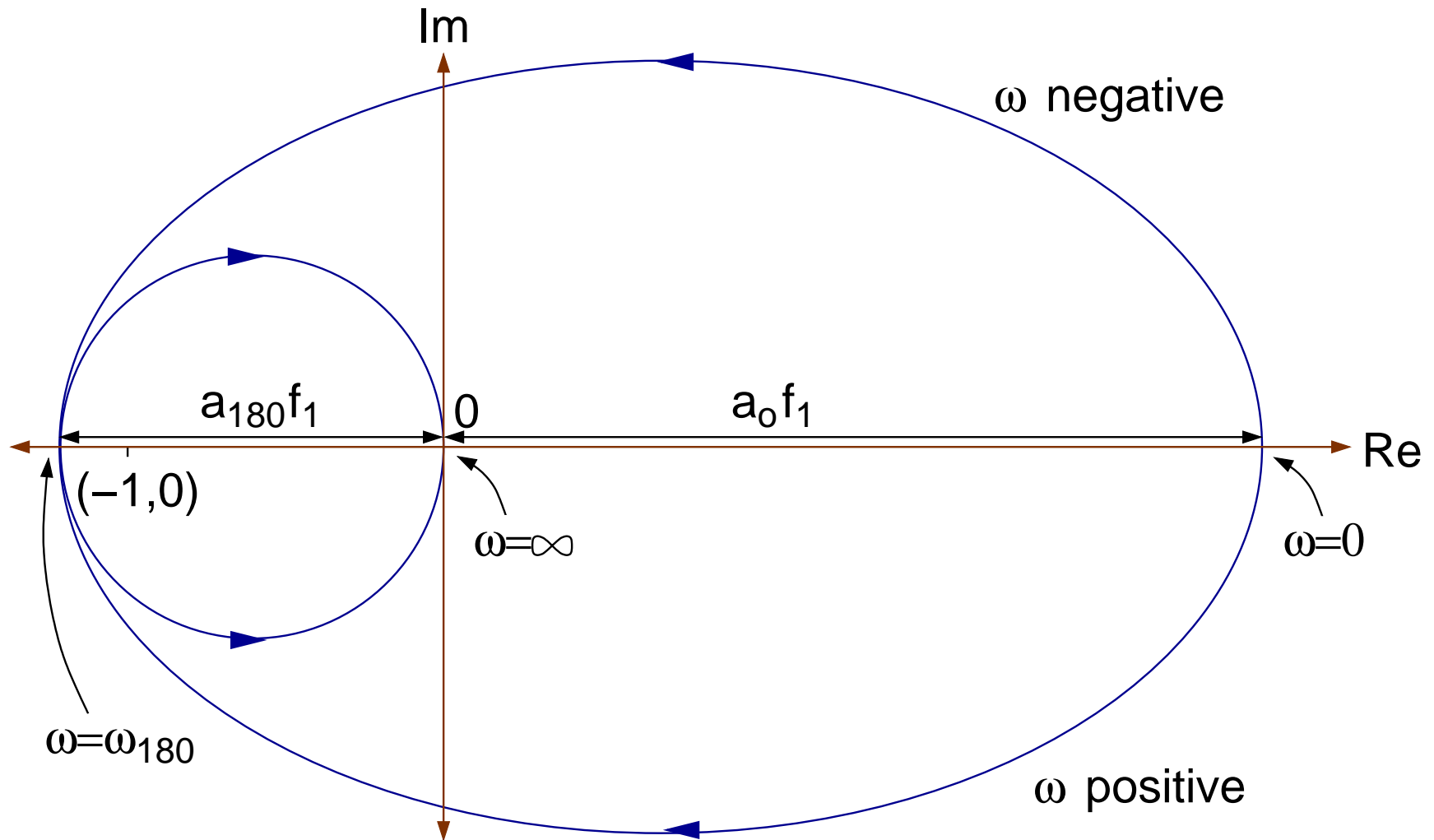
Magnitude & Phase

$$T(s) = a(s)f_1$$



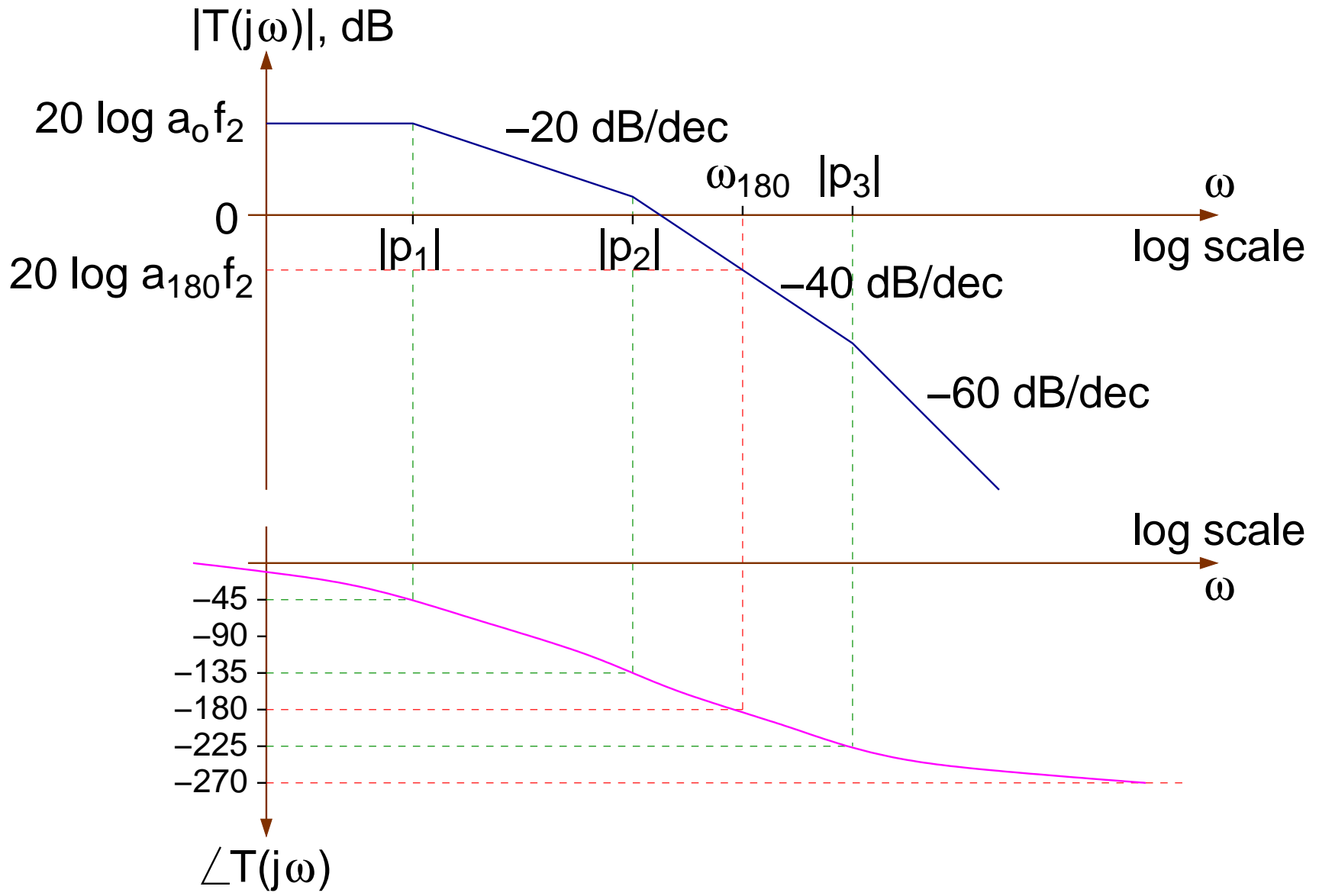
Nyquist Plot

$$T(s) = a(s)f_1$$



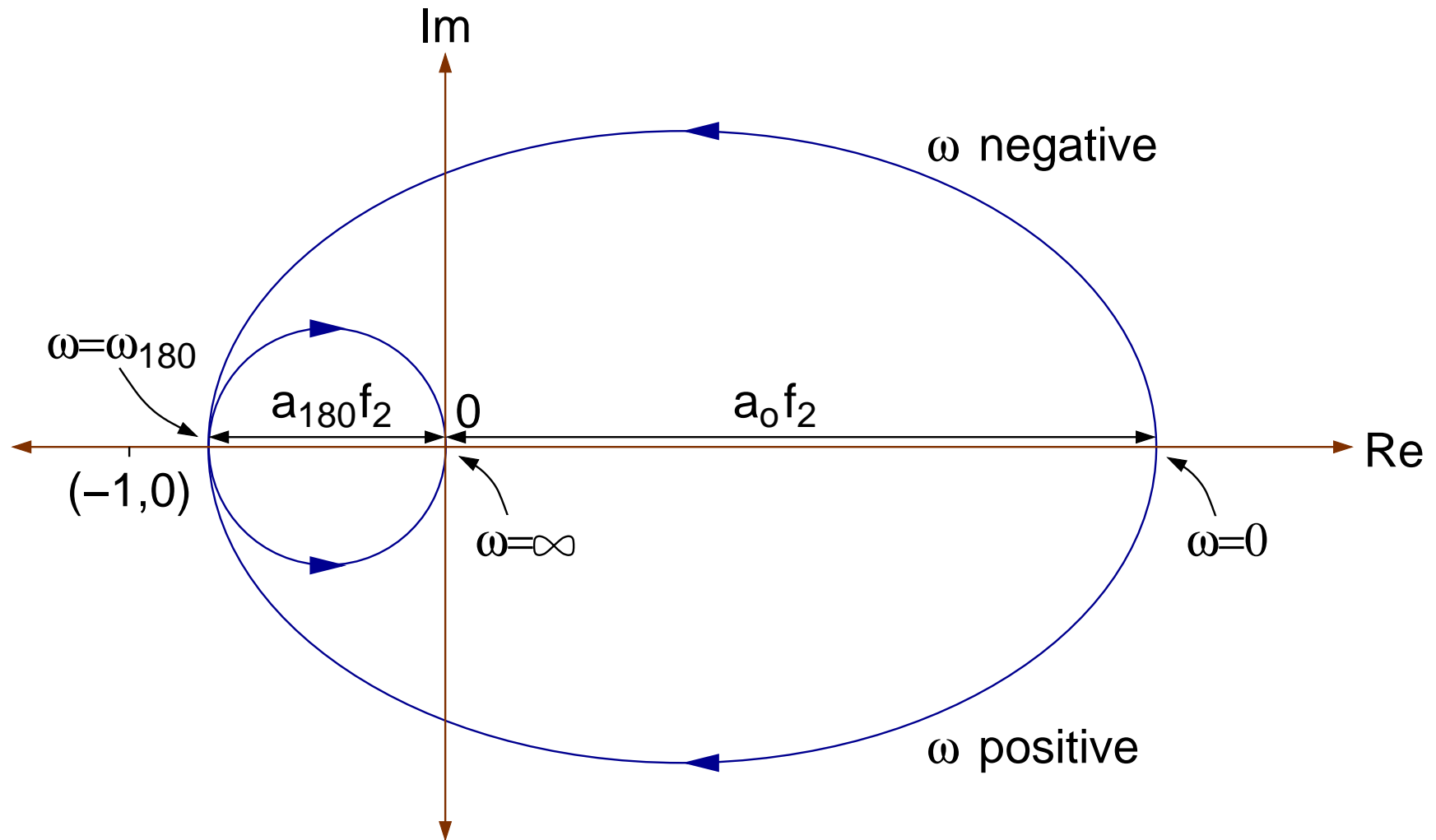
Magnitude & Phase

$$T(s) = a(s)f_2$$

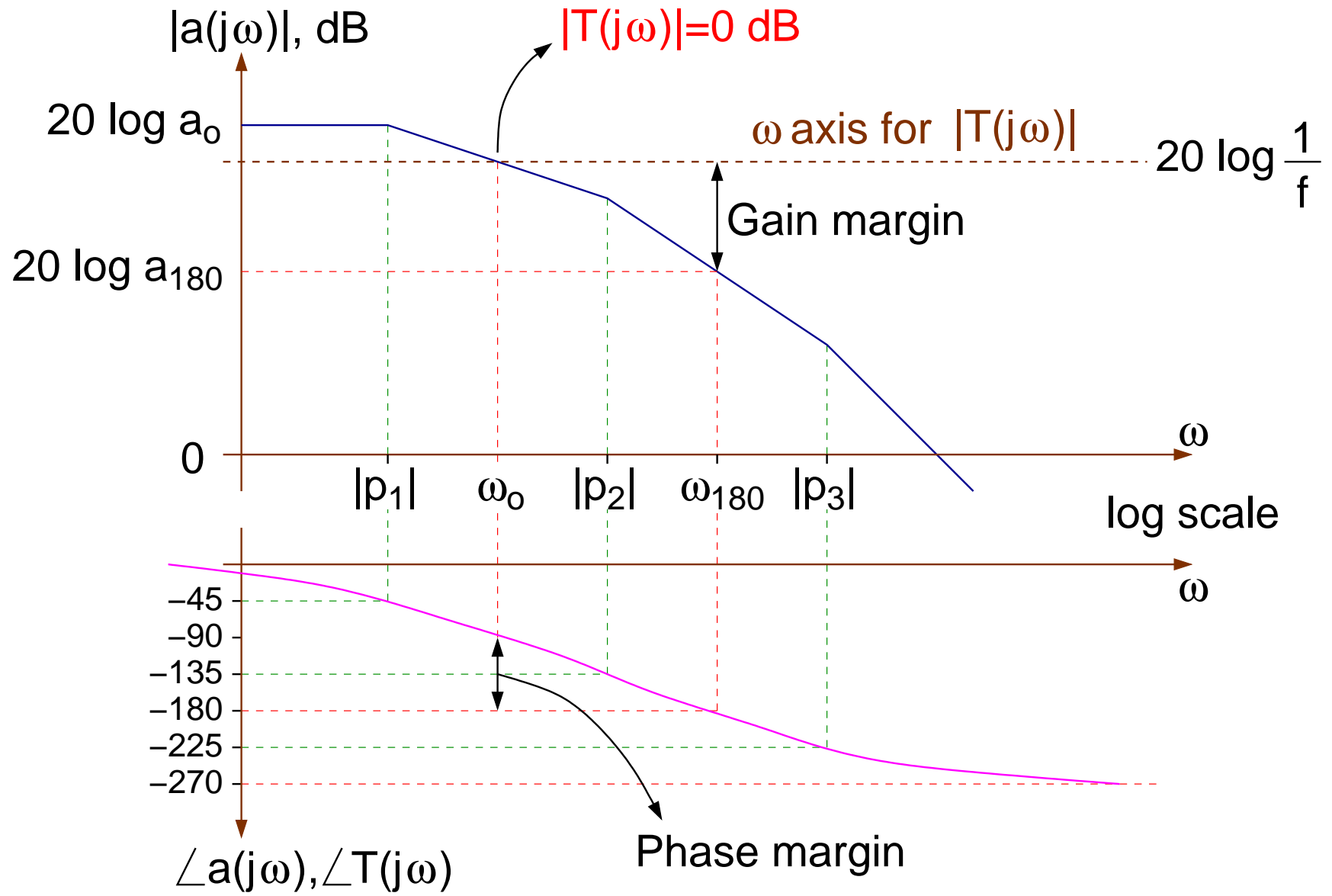


Nyquist Plot

$$T(s) = a(s)f_2$$



Gain & Phase Margin



Stability Criteria

Nyquist:

$$|T(j\omega_{180})| = a_{180}f < 1 \Rightarrow \text{Stable}$$

Gain Margin (**GM**):

$$\text{GM} = 20 \log \frac{1}{|T(j\omega_{180})|} = -20 \log |T(j\omega_{180})|$$
$$\text{GM} > 0 \Rightarrow \text{Stable}$$

Phase Margin (**PM**):

$$\text{PM} = 180^\circ + \angle T(j\omega_o)$$
$$\text{PM} > 0 \Rightarrow \text{Stable}$$

Phase Margin

$$|T(j\omega_0)| = 1 \Rightarrow |a(j\omega_0)|f = 1 \Rightarrow |a(j\omega_0)| = \frac{1}{f}$$

$$PM = 45^\circ \Rightarrow \angle T(j\omega_0) = -135^\circ, \quad A(j\omega_0) = \frac{a(j\omega_0)}{1 + T(j\omega_0)}$$

$$A(j\omega_0) = \frac{a(j\omega_0)}{1 + e^{-j135^\circ}} = \frac{a(j\omega_0)}{1 - 0.7 - 0.7j}$$

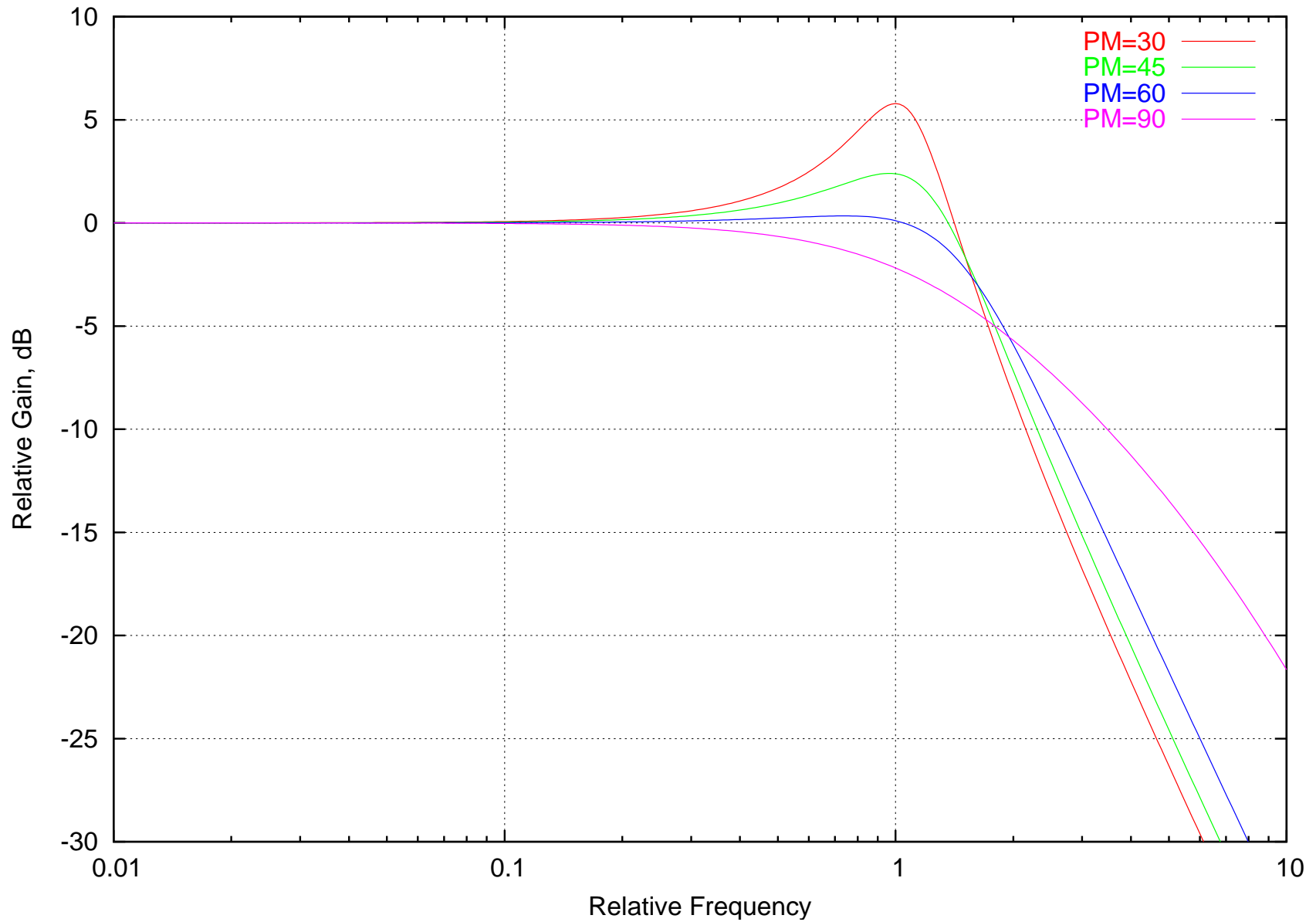
$$|A(j\omega_0)| = \frac{|a(j\omega_0)|}{|0.3 - 0.7j|} = \frac{1}{0.76f} = \frac{1.3}{f}$$

$$PM = 30^\circ \Rightarrow \angle T(j\omega_0) = -150^\circ, \quad |A(j\omega_0)| = 1.92/f$$

$$PM = 60^\circ \Rightarrow \angle T(j\omega_0) = -120^\circ, \quad |A(j\omega_0)| = 1/f$$

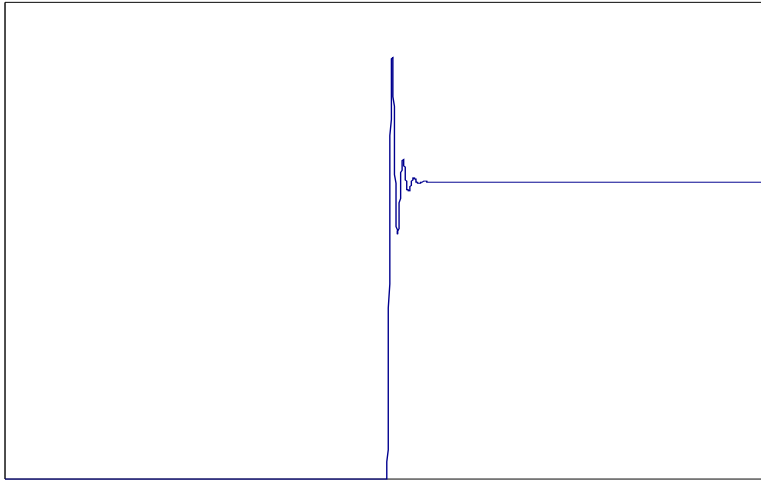
$$PM = 90^\circ \Rightarrow \angle T(j\omega_0) = -90^\circ, \quad |A(j\omega_0)| = 0.7/f$$

Closed-Loop Frequency Response



Closed-Loop Step Response

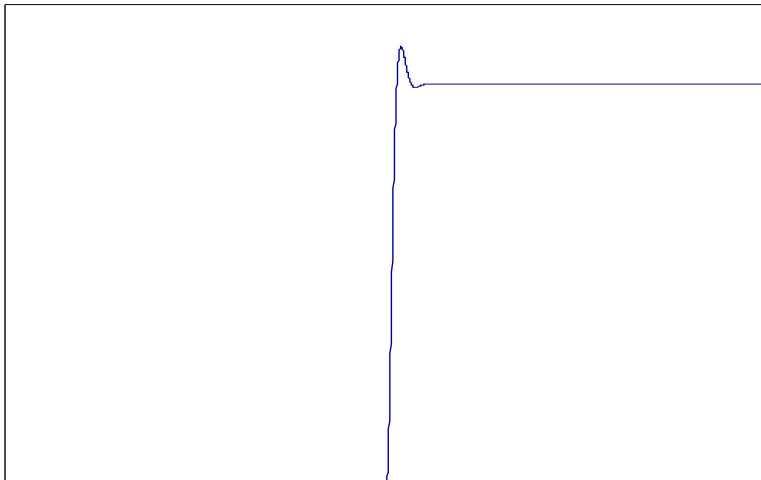
PM = 30°



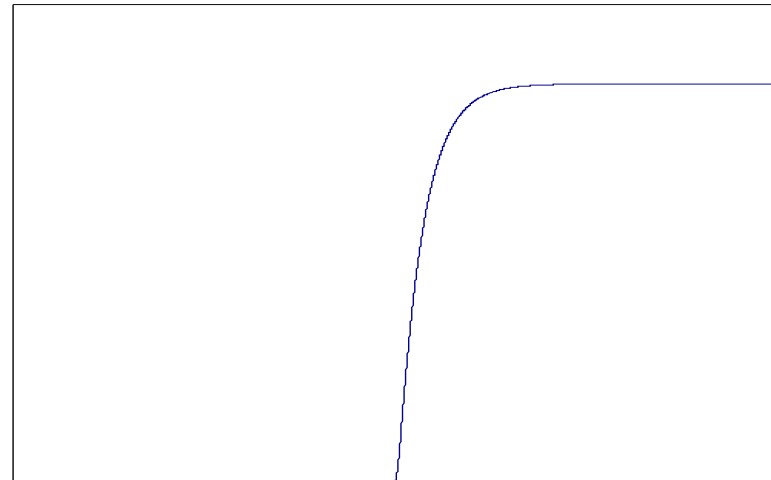
PM = 45°



PM = 60°

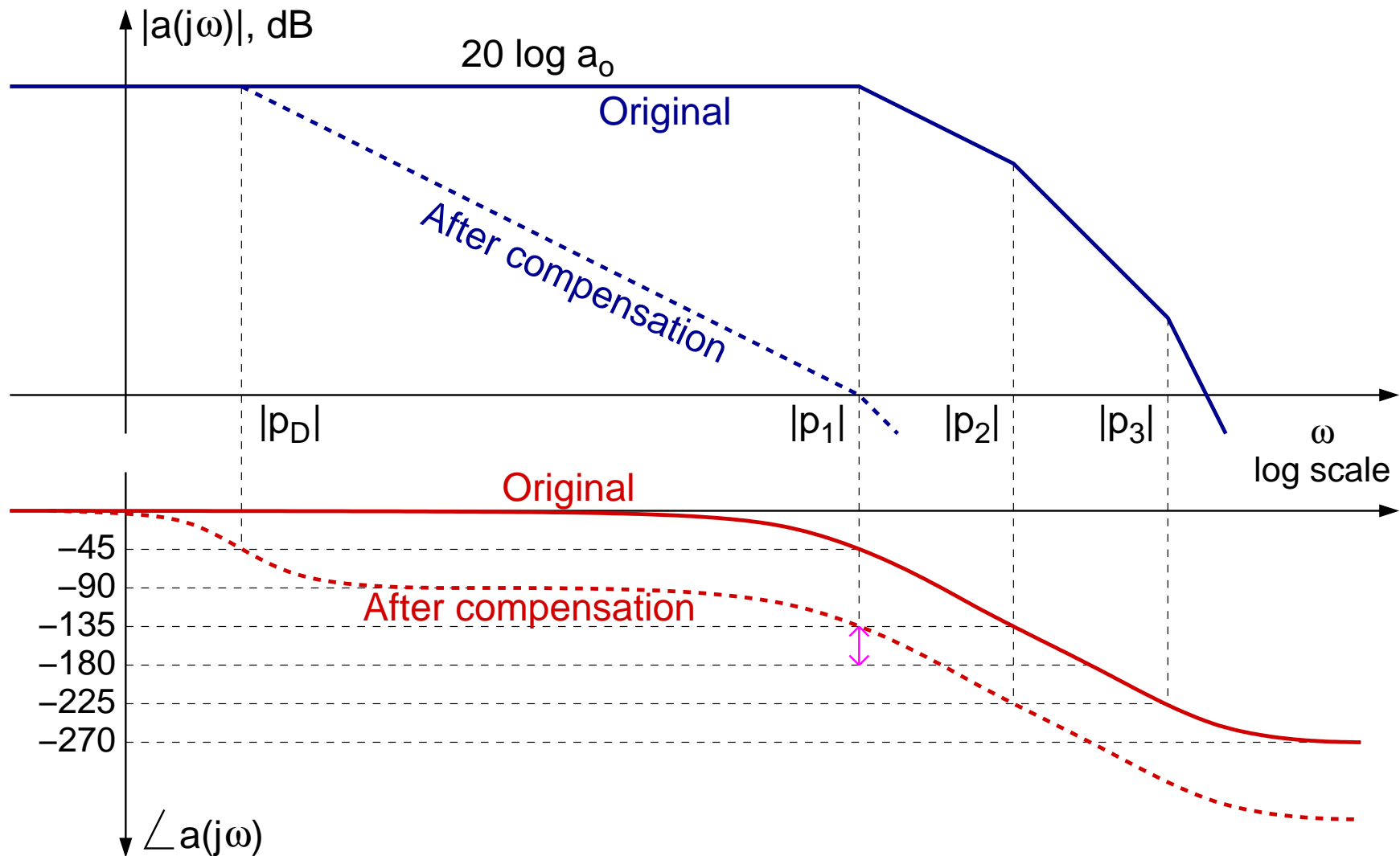


PM = 90°



Compensation

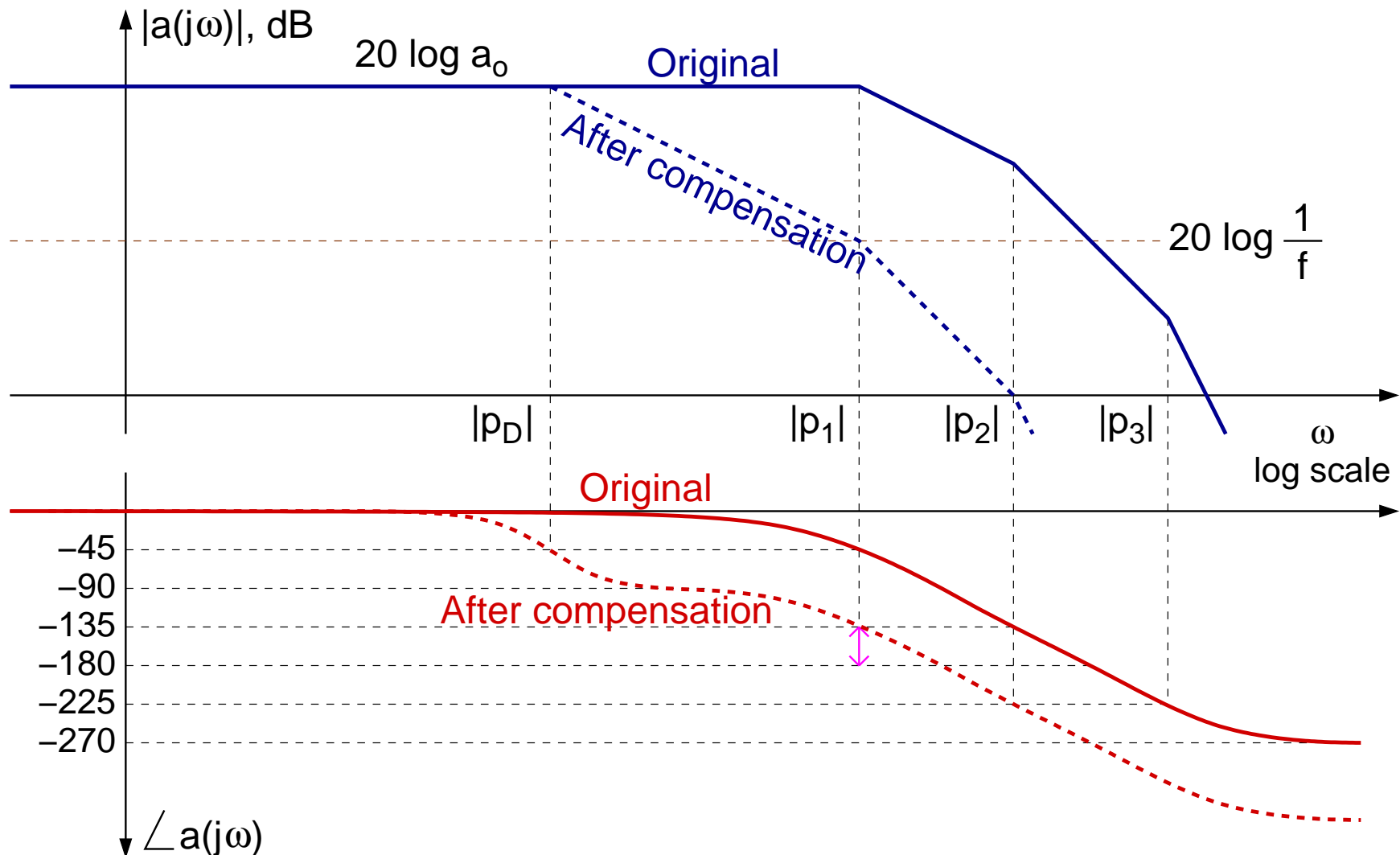
Dominant pole (p_D) added, $f = 1$



$$|p_D| \approx |p_1|/a_0$$

Compensation

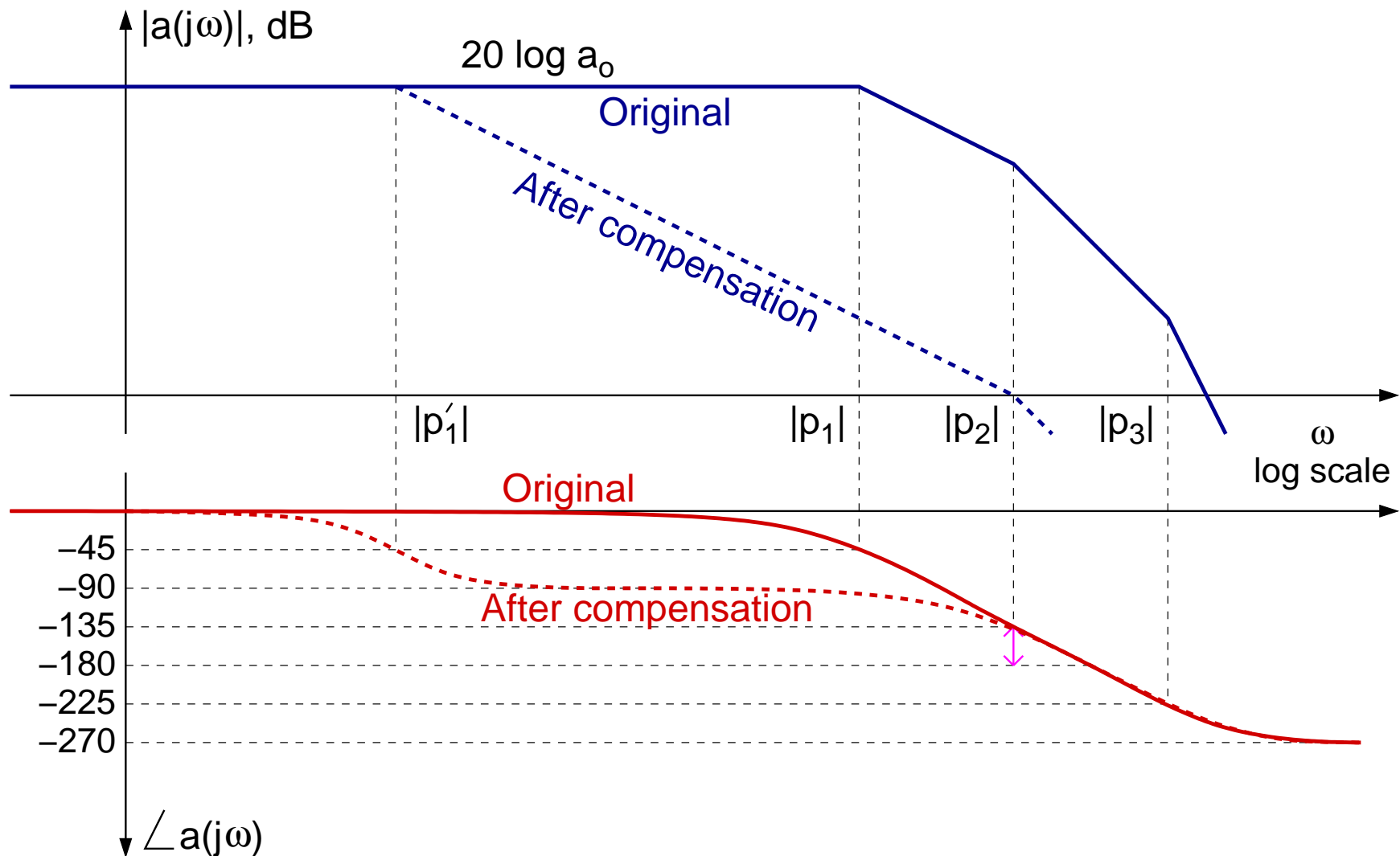
Dominant pole (p_D) added, $f < 1$



$$|p_D| \approx |p_1| / (a_o f)$$

Compensation

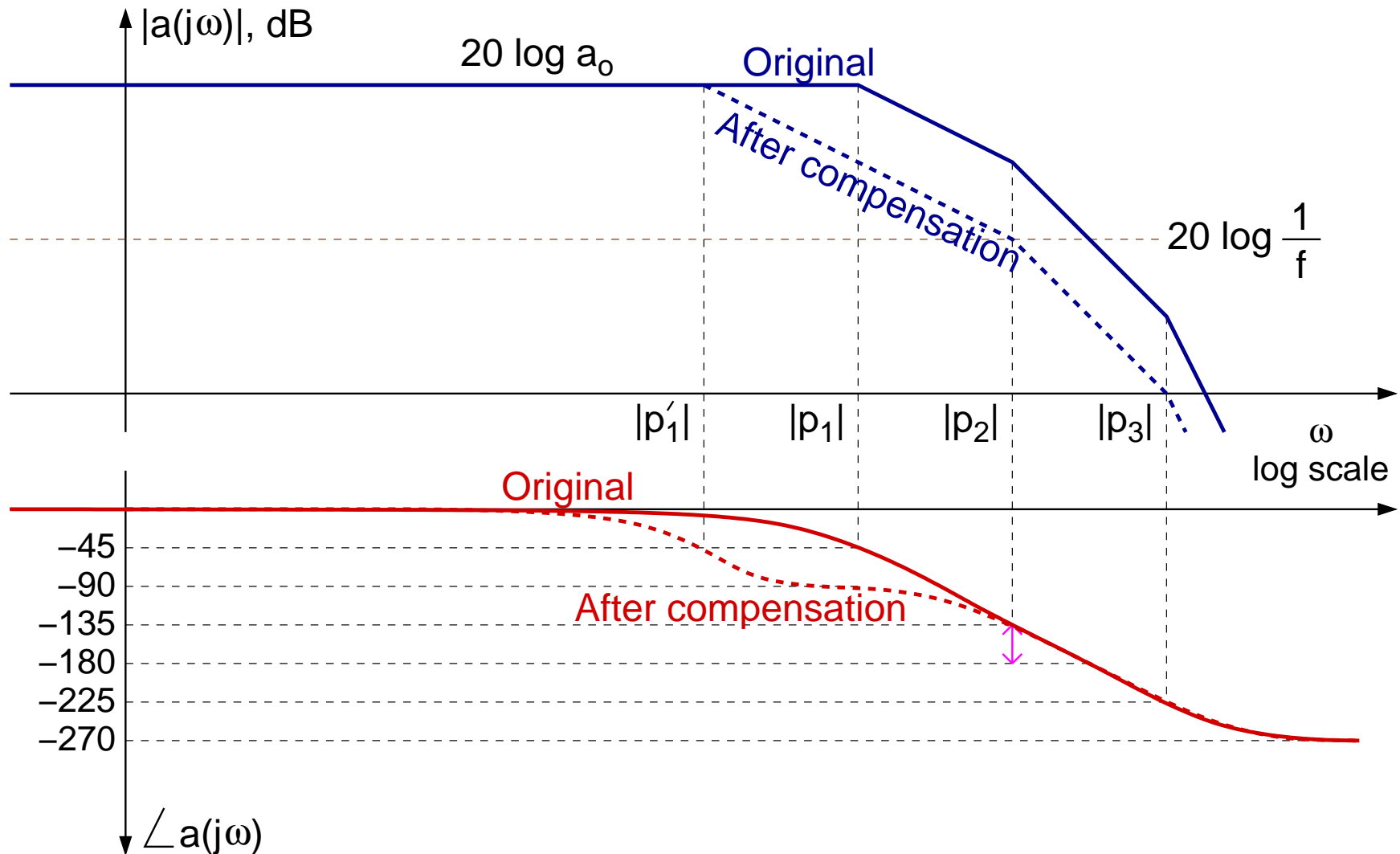
p_1 shifted to p'_1 , $f = 1$



$$|p'_1| \approx |p_2|/a_0$$

Compensation

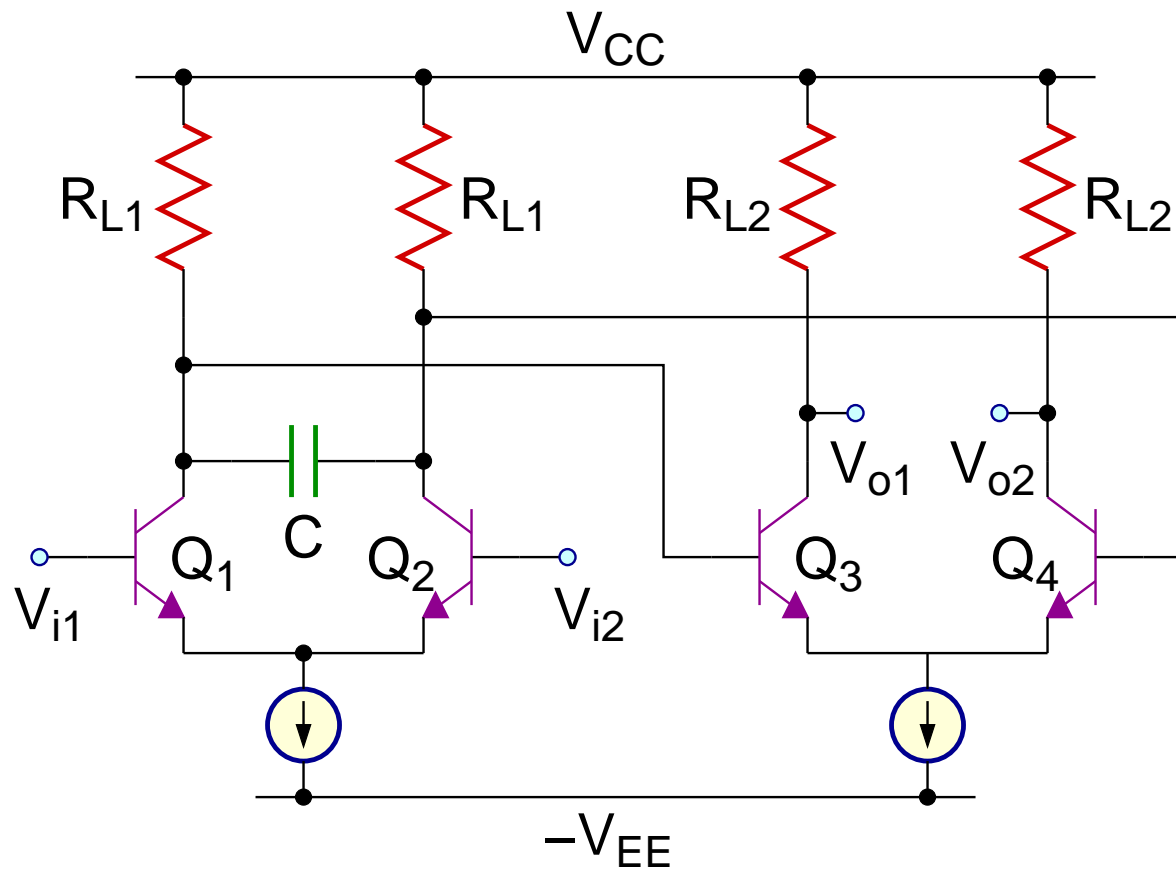
p_1 shifted to p'_1 , $f < 1$



$$|p'_1| \approx |p_2| / (a_0 f)$$

2-Stage Amplifier

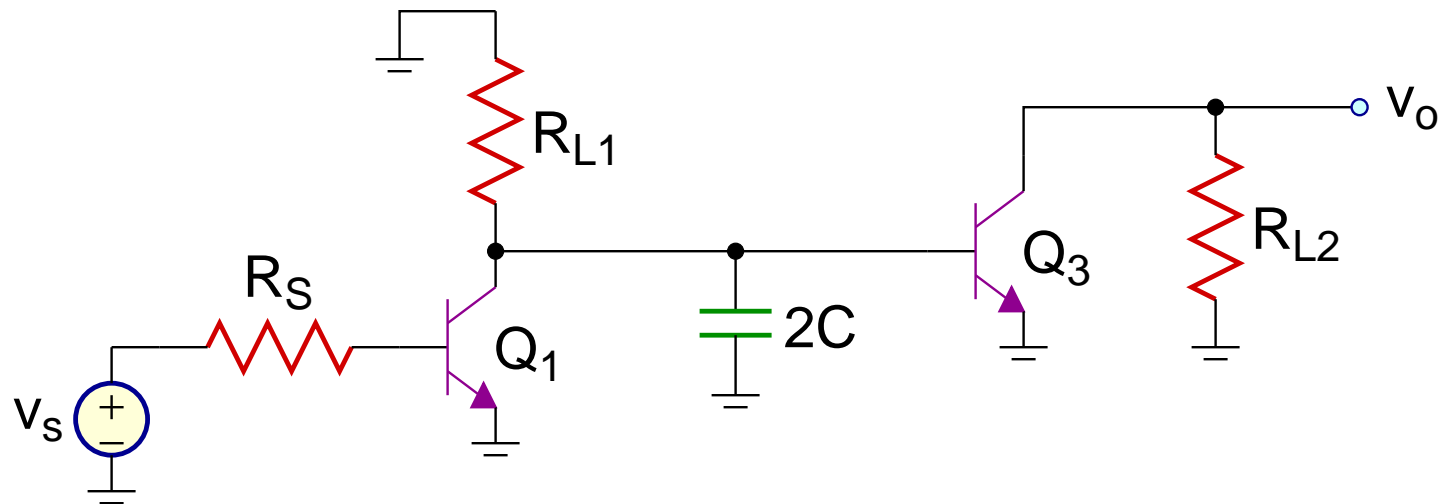
Dominant-pole compensation



C : Compensation capacitor

2-Stage Amplifier

DM half circuit



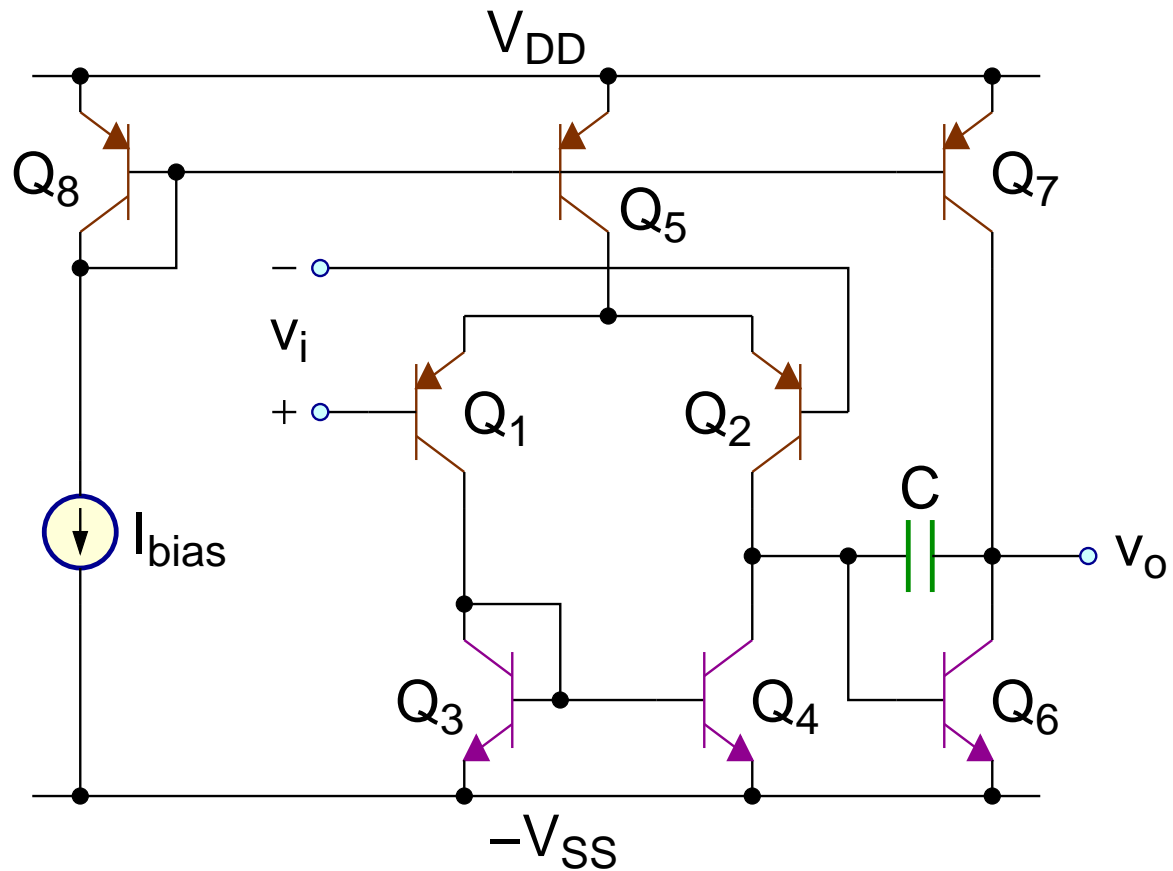
$$|p_D| = \frac{1}{2RC}$$

$$R = R_{L1} \parallel (r_{b3} + r_{\pi3})$$

The value of **C** required is usually very large (typically $> 1\text{nF}$)

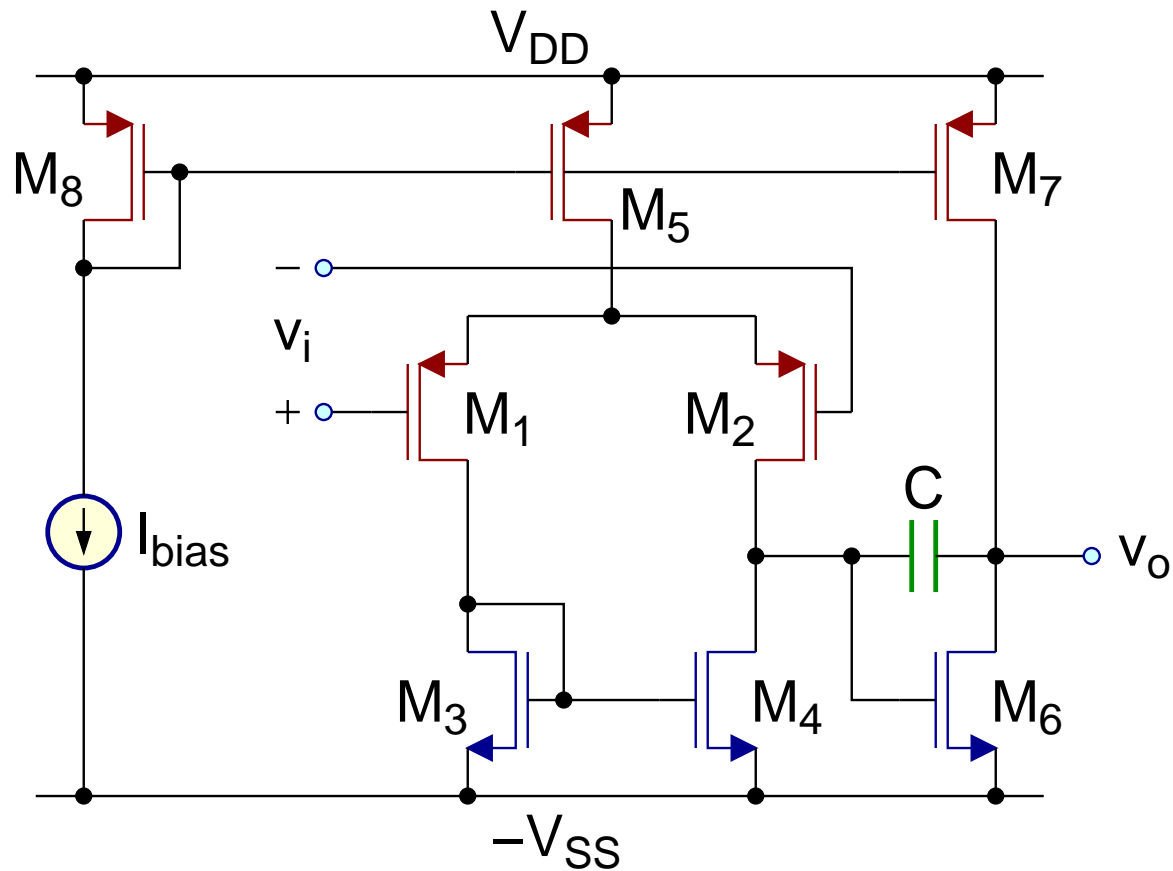
Compensation of Opamps

Simplified BJT



C : Compensation capacitor

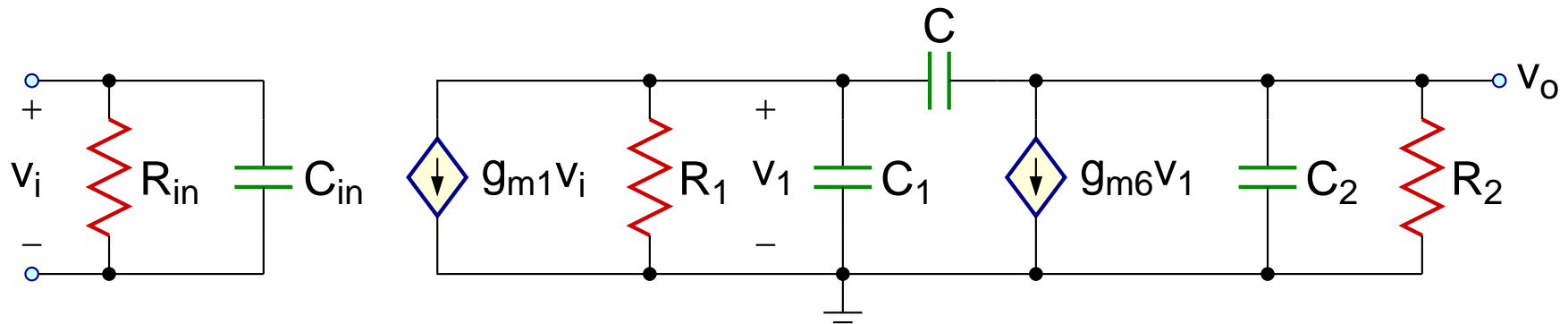
Compensation of Opamps



C : Compensation capacitor

Compensation of Opamps

Small-signal equivalent



$$\frac{v_o}{v_i} = \frac{g_{m1} R_1 R_2 (g_{m6} - sC)}{1 + s[R_1(C_1 + C) + R_2(C_2 + C) + g_{m6} R_1 R_2 C] + s^2[R_1 R_2 (C_1 C_2 + C C_1 + C C_2)]}$$

If $\mathbf{p_1}$ and $\mathbf{p_2}$ are real, $|\mathbf{p_1}| \ll |\mathbf{p_2}|$, \mathbf{C} is large,
 $\mathbf{g_{m6} R_1}, \mathbf{g_{m6} R_2} \gg \mathbf{1}$:

$$p_1 \approx -\frac{1}{R_1(C_1 + C) + R_2(C_2 + C) + g_{m6} R_1 R_2 C} \approx -\frac{1}{g_{m6} R_1 R_2 C}$$

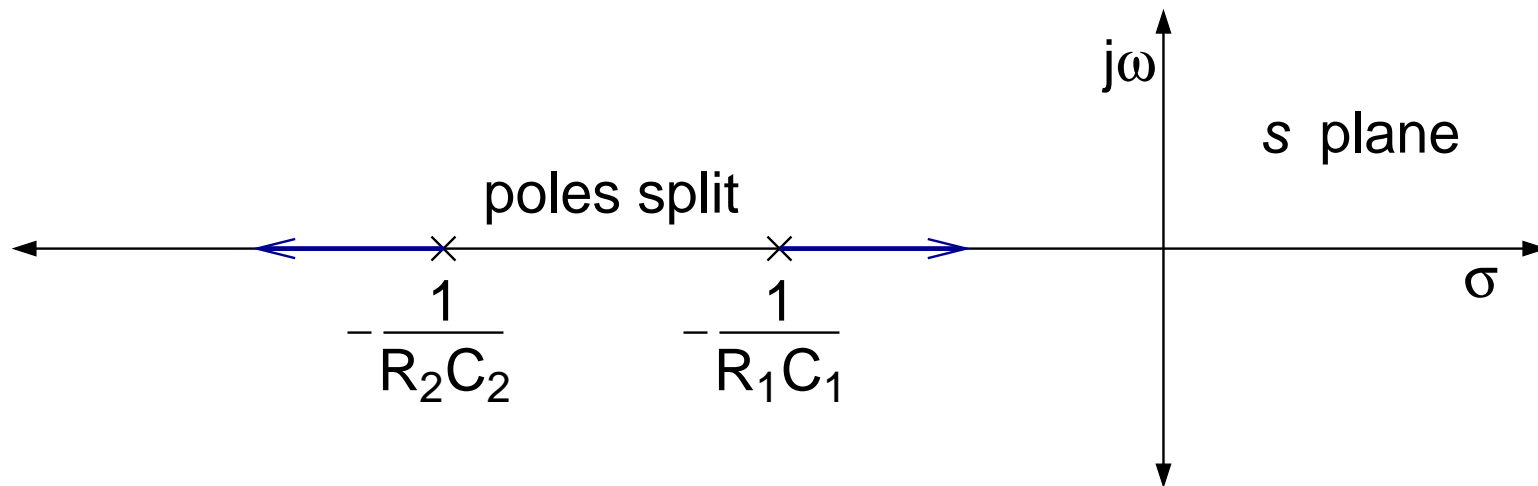
$$p_2 \approx -\frac{g_{m6} C}{C_1 C_2 + C(C_1 + C_2)} \quad z = \frac{g_{m6}}{C}$$

Compensation of Opamps

Pole splitting

$$C = 0 \Rightarrow p_1 = -\frac{1}{R_1 C_1}, \quad p_2 = -\frac{1}{R_2 C_2}$$

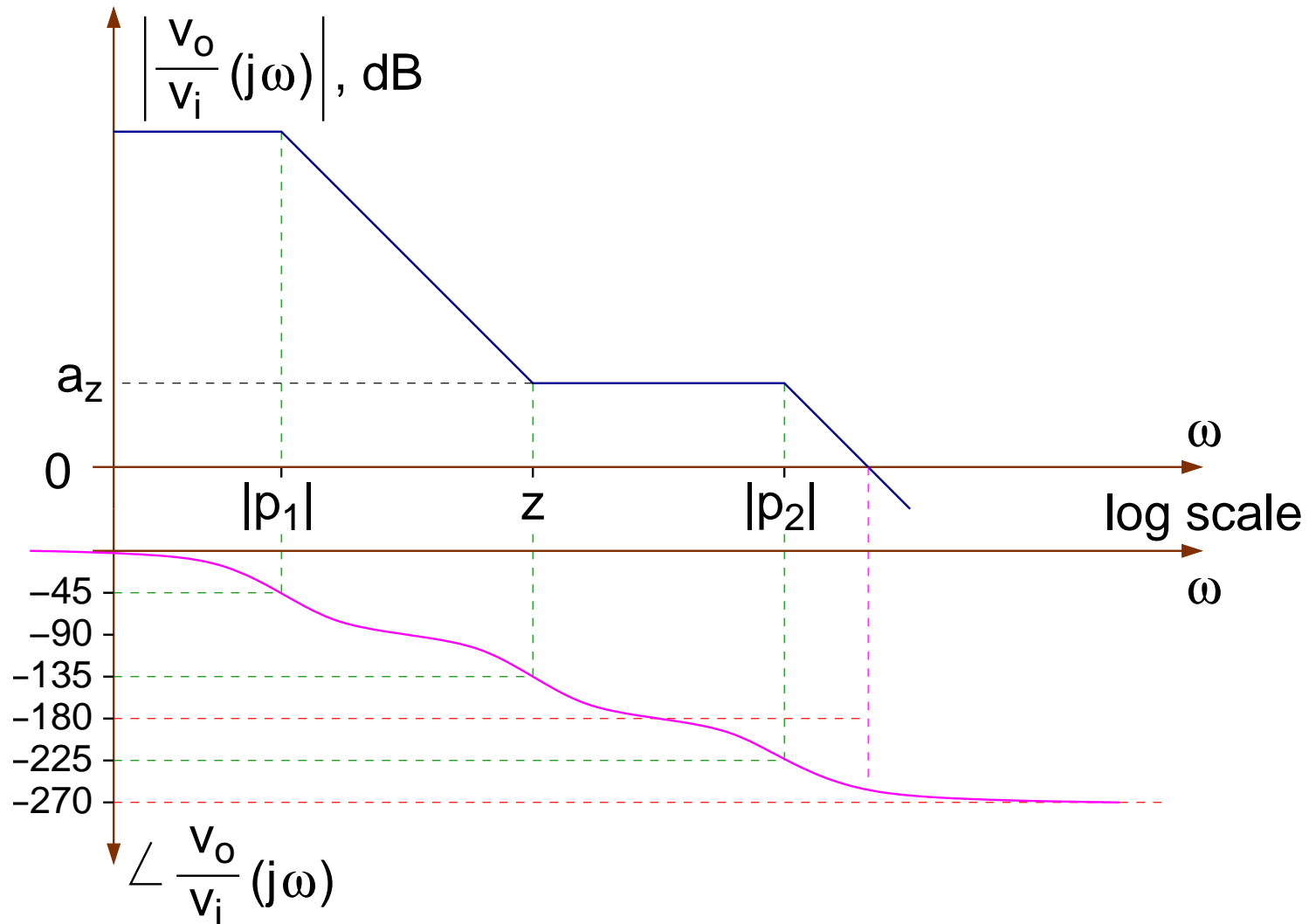
$$C \gg C_1, C_2 \Rightarrow p_1 \approx -\frac{1}{g_{m6} R_1 R_2 C}, \quad p_2 \approx -\frac{g_{m6}}{C_1 + C_2}$$



As C increases, $|p_1|$ decreases and $|p_2|$ increases

Effect of RHP Zero

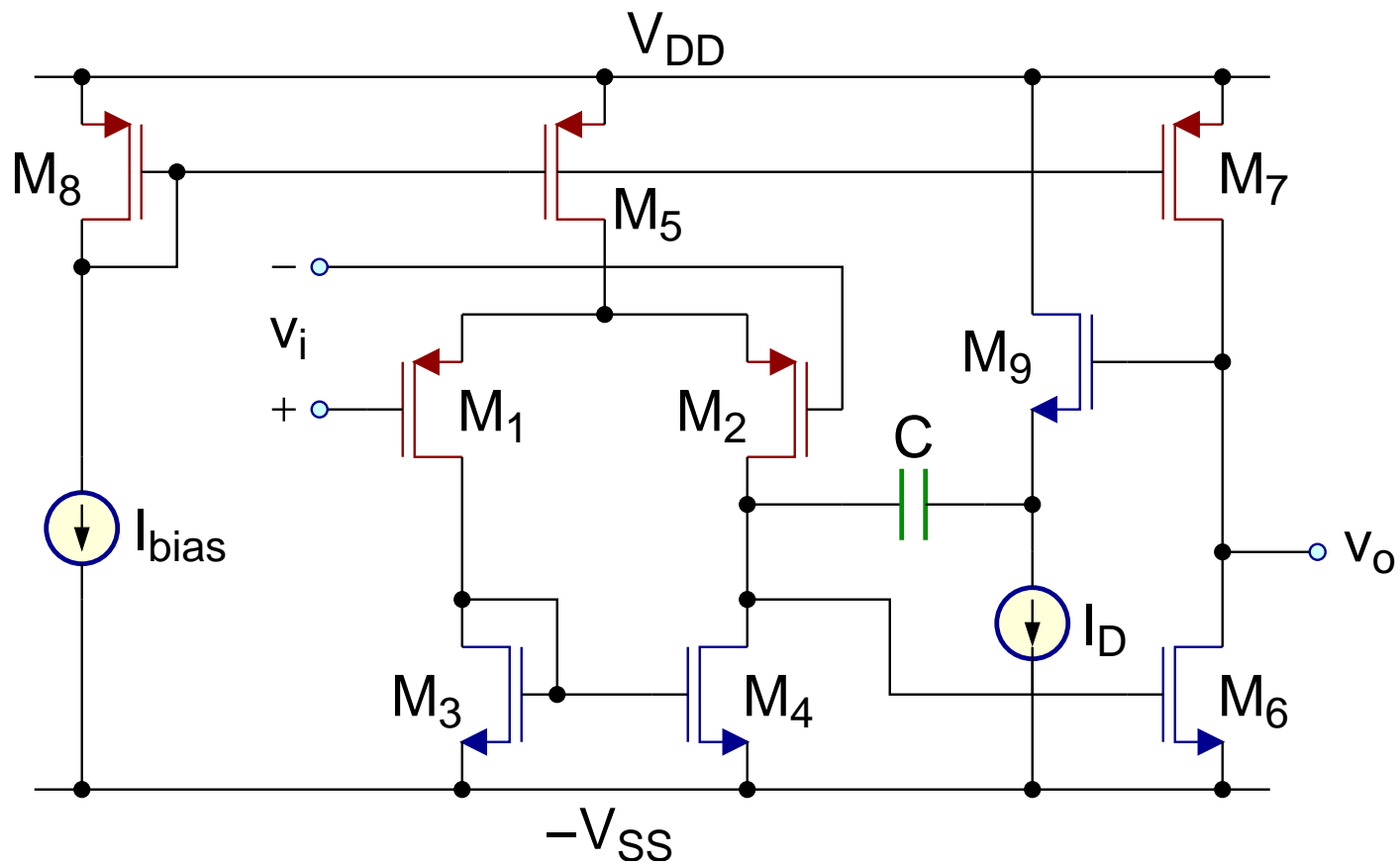
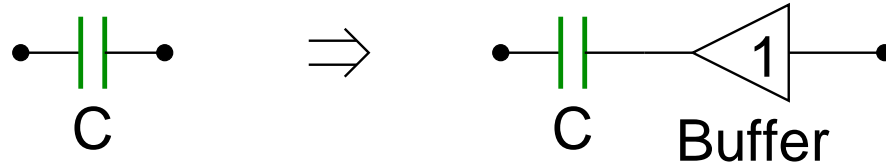
$$z = g_{m6}/C$$



If $a_z > 0$ dB and $z < |p_2|$, PM becomes negative

Elimination of RHP Zero Effect

Solution #1



Elimination of RHP Zero Effect

Solution #1

Assuming $g_{m6}R_1, g_{m6}R_2 \gg 1$ and C is large,

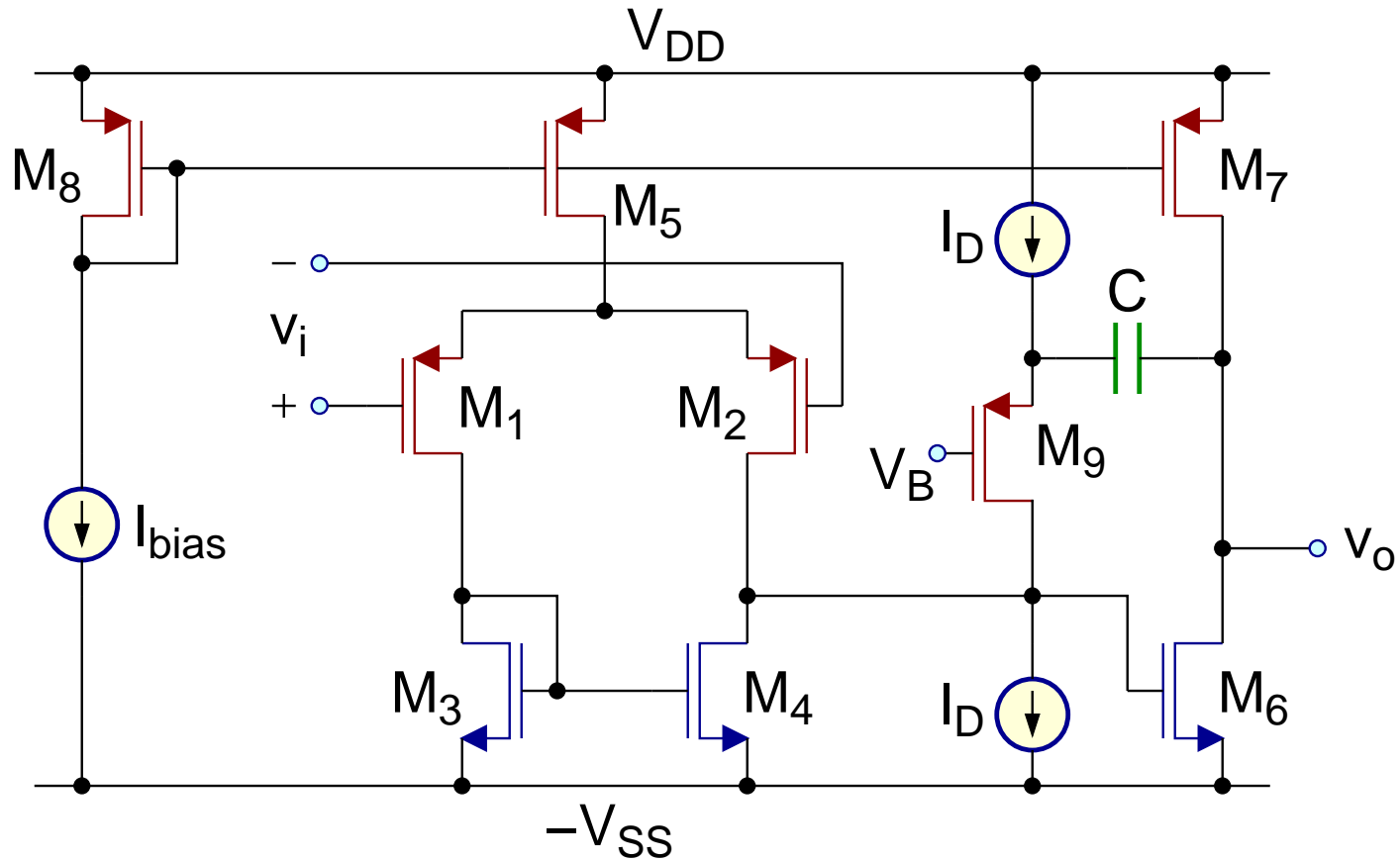
$$p_1 \approx -\frac{1}{g_{m6}R_1R_2C}$$

$$p_2 \approx -\frac{g_{m6}C}{(C_1 + C)C_2} \approx -\frac{g_{m6}}{C_2}$$

- The zero has been eliminated
- p_1 is unchanged
- p_2 is approximately the same as before
- Extra devices and bias current are required
- Output swing is affected

Elimination of RHP Zero Effect

Solution #2



Elimination of RHP Zero Effect

Solution #2

Assuming $g_{m6}R_1, g_{m6}R_2 \gg 1$ and C is large,

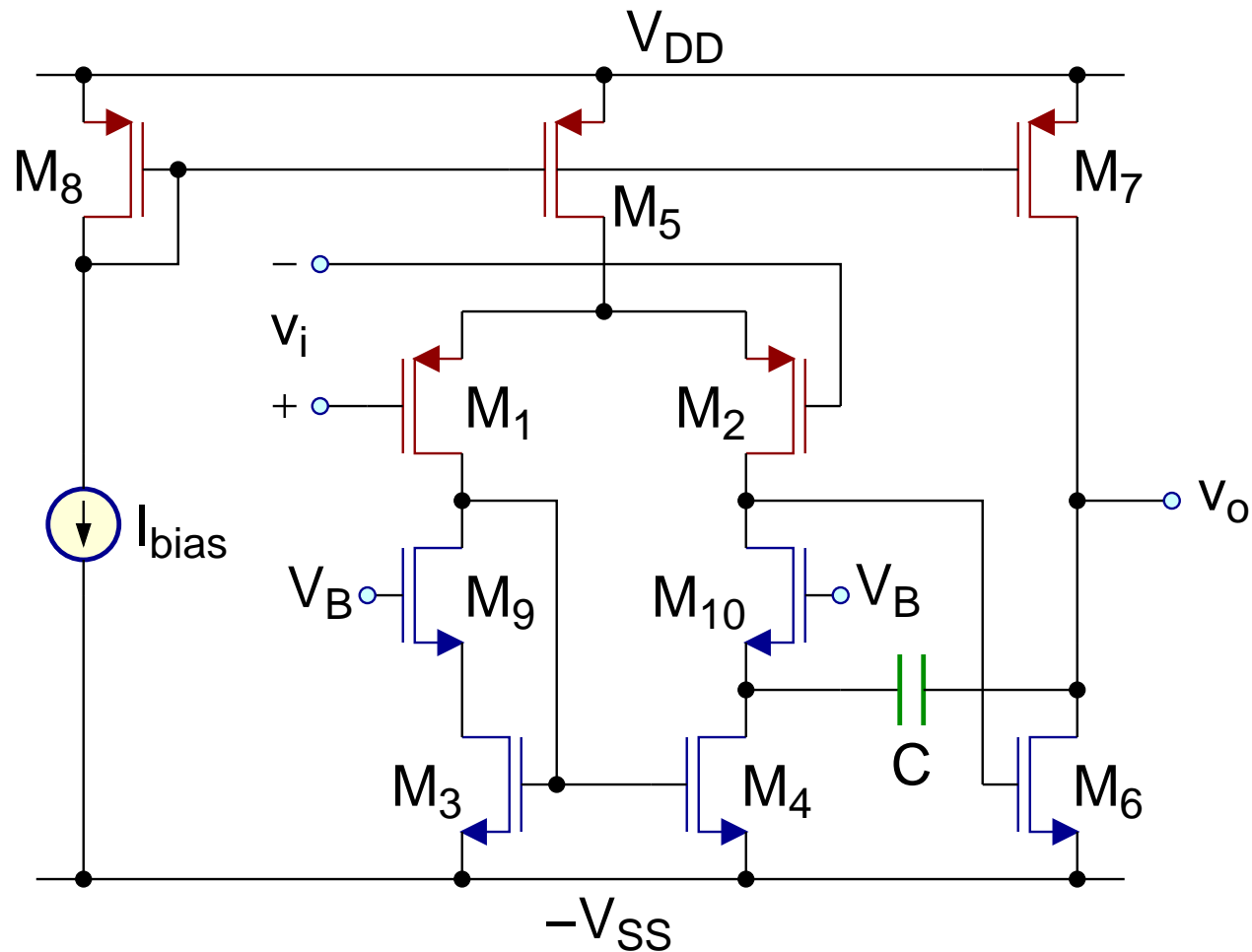
$$p_1 \approx -\frac{1}{g_{m6}R_1R_2C}$$

$$p_2 \approx -\frac{g_{m6}}{C + C_2} \frac{C}{C_1}$$

- The zero has been eliminated
- p_1 is unchanged
- p_2 is at a higher frequency
- Extra devices and bias current are required
- Input offset voltage is affected if I_D s mismatch

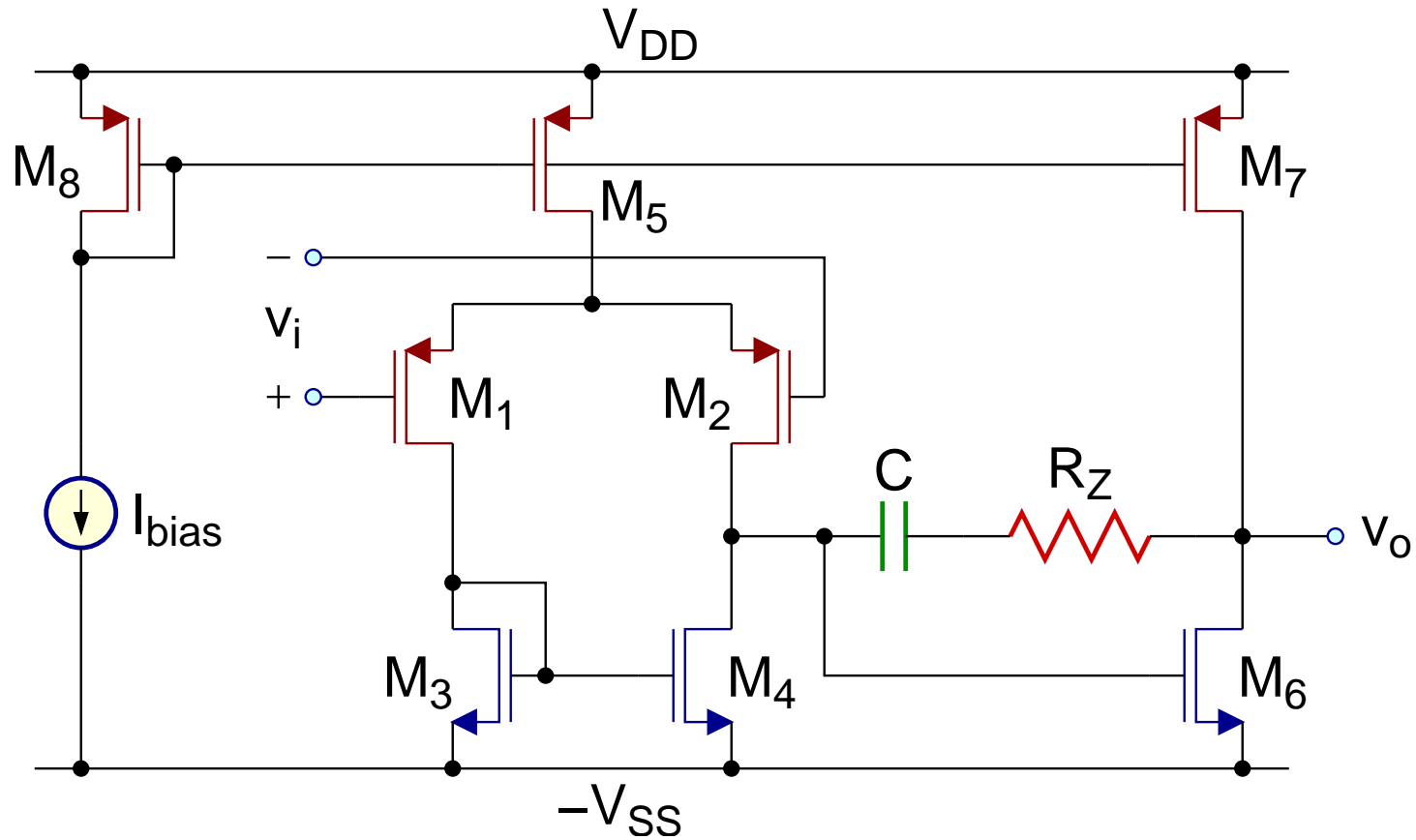
Elimination of RHP Zero Effect

Solution #2 - alt.



Elimination of RHP Zero Effect

Solution #3



Elimination of RHP Zero Effect

Solution #3

Assuming $g_{m6}R_1, g_{m6}R_2 \gg 1$ and C is large,

$$p_1 \approx -\frac{1}{g_{m6}R_1R_2C}$$

$$p_2 \approx -\frac{g_{m6}C}{C_1C_2 + C(C_1 + C_2)} \approx -\frac{g_{m6}}{C_1 + C_2}$$

$$p_3 \approx -\frac{1}{R_ZC_1}$$

$$z = \frac{1}{\left(\frac{1}{g_{m6}} - R_Z\right)C}$$

$$R_Z = \frac{1}{g_{m6}} \Rightarrow z = \infty$$

$$R_Z > \frac{1}{g_{m6}} \Rightarrow \text{LHP zero } (z < 0)$$