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| Course title and number    | <b>Linear Multivariable Systems, ECEN 605</b> |
| Term                       | Fall 2017                                     |
| Meeting times and location | To be arranged (3 hours lectures, 1 hour lab) |

## Course Description and Prerequisites

The course deals with single input single output systems, multivariable systems, the linear servomechanism problem, and linear quadratic optimal control. The emphasis is on linear systems and a thorough coverage of classical linear control theory and modern state space control theory is given. It is assumed that the student has had an undergraduate course in Control Systems and has a working knowledge of a programming language such as Matlab. A detailed listing of topics and a weekly schedule follows:

### 1. Single input Single output systems

- 1.1 Laplace Transform Review
- 1.2 Linear Algebra Review
- 1.3 Static and Dynamic Models
- 1.4 State Variable and Transfer Function Models
- 1.5 Stability and Stabilization
- 1.6 Tracking, disturbance rejection and pole placement
- 1.7 Classical control, Nyquist criterion and stability margins

### 2. Multivariable Systems

- 2.1 Realization Theory
- 2.2 State Feedback
- 2.3 Observers

### 3. Linear Servomechanism problem

- 3.1 Problem formulation

3.2 Internal models

3.3 Existence conditions

3.4 Closed-loop structure

#### 4. Linear Quadratic Optimal Control

4.1  $H_2$  optimal control Linear Quadratic Regulator (LQR)

4.2  $H_\infty$  optimal control

| Weekly Schedule of Topics |  |
|---------------------------|--|
| Week 1                    | Laplace Transform Review                                   |
| Week 2                    | Linear Algebra Review                                      |
| Week 3                    | Static and Dynamic Models                                  |
| Week 4                    | State Variable and Transfer Function Models                |
| Week 5                    | Stability and Stabilization                                |
| Week 6                    | Tracking, disturbance rejection and pole placement         |
| Week 7                    | Classical control, Nyquist criterion and stability margins |
| Week 8                    | Realization Theory   |
| Week 9                    | State Feedback   |
| Week 10                   | Observers  |
| Week 11                   | Linear Servomechanism problem                              |
| Week 12                   | Internal models  |
| Week 13                   | $H_2$ optimal control Linear Quadratic Regulator (LQR)     |
| Week 14                   | $H_\infty$ optimal control                                 |

### Instructor Information

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### Textbook and/or Resource Material

References: - Linear Systems, T. Kailath,  
- Linear Systems, P. J. Antsaklis and A. N. Michel.

### Grading Policies

#### Assignments and Tests

**Homework will be assigned approximately every two weeks. (Total 7 assignments)**

**Tests will be administered once every four weeks (Total 3 tests)**

- All Homeworks are required.
- There will be three tests
- Homework grade is worth 60%.
- Test grade is worth 40%.

### Grading Scale

*Standard Letter Grading Scale:*

A = 90-100  
B = 80-89  
C = 70-79  
D = 60-69  
F = <60

**Attendance and make-up policies:** Please refer to <http://student-rules.tamu.edu/rule07>

### **Americans with Disabilities Act (ADA)**

The Americans with Disabilities Act (ADA) is a federal anti-discrimination statute that provides comprehensive civil rights protection for persons with disabilities. Among other things, this legislation requires that all students with disabilities be guaranteed a learning environment that provides for reasonable accommodation of their disabilities. If you believe you have a disability requiring an accommodation, please contact Disability Services, currently located in the Disability Services building at the Student Services at White Creek complex on west campus or call 979-845-1637. For additional information, visit <http://disability.tamu.edu>.

### **Academic Integrity**

*For additional information please visit: <http://aggiehonor.tamu.edu>*

*“An Aggie does not lie, cheat, or steal, or tolerate those who do.”*